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TALES FROM THE ARCHITECT

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Part 3 : The Archangel of Time

Tales from the Architect: The Archangel of Time

Tejaswi P Ramesh

June 2025

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1 The mechanics of territory economy

Let there be a territory or a boundary defined by an area of "R " units defined by a circle with the location of the origin at o.

Let there be the masculine of the territory located at the location " o ". The definition of the masculine under this context could be defined as the point that has the energy source for the movement in the circle

Let there be " n " individuals in the circle who are located at " n " points.

Let there be movement of the (n+1) individuals in the defined circle.

The purpose of the movement could be survival, nonsurvival, and reproductive needs.

Survival needs

The survival needs in the circle could be defined as the ability for movement that could be interpreted as a source of energy that enables movement.

The trajectory of the movement could be defined by the attention vector of each individual point that drives the movement toward the location with the source of energy which is the masculine who is located at the origin o.

Non Survival needs

The nonsurvival needs in the circle could be defined as the movement that occurs when there is no need for the energy source for movement. In another context, the movement for which the energy source was absorbed.

The movement for nonsurvival needs could occur depending on the attention vector of the individual.

Reproductive needs

The reproductive needs in the circle could be defined as the movement that occurs when there is a need to create another point. The attention vector of each of the points directs the movement toward the location where there is an energy source for reproduction.

The purpose of reproduction could be defined both by survival and non-survival needs. Since the new point that is created is also directed toward the origin as a result of the energy source, the masculine could indirectly play a part in reproduction.

This is because if there is a correlation between the amount of energy that is located at the point o and the consumption of energy from the " n " individuals in the circle, it could be measured through the following metrics:

The amount of energy consumed by each of the " n " individual points for its movement. The effect of the energy consumption from the " n " individuals at the point o and consequently the total energy available in the circle. The effect of individual movement from " n " individuals between each other and consequently the territory.

1.1 The consequences of the collective movement

The radius of the circle defined by the origin increases which is called territory expansion.

The radius of the circle defined by the origin increases which is called territory contraction.

Therefore every movement that occurs within the sphere of influence of the point o could be accessible to the masculine at " o " because the movement vector that defines the trajectory for the " n " points for their survival, nonsurvival, and reproductive needs occurs through the quantum entanglement between the attention vector of the masculine " o " and each of the " n " points.

The instinct that defines the movement for each of the " n " individuals is directed towards the locations for their current needs and the locations defined by the masculine for each of these needs.

1.2 The categorization of instinct

Therefore the instinct that drives the movement of each individual could be based on two inputs for the attention vector of the individuals.

The territory tree hierarchy is where the directional information flows from the origin to the other individuals on a collective territory-wide based on their location. The family tree hierarchy is where the directional information flows from their interactions along their movement such that they could establish masculinity or become an energy source so that they have their own sphere or territory of influence.

Since the family tree instincts are learned through various interactions that occur specifically the acquisition of energy sources, the family instincts that increase the probability of outward expansion are the movement instincts that correlate the following :

The current stored energy by each masculine at the origin of his territory and the movement patterns that are occurring as a result of the individuals trying to acquire these energy sources define the " state " of the territory. The collective movement that occurs as a result of this process could be defined as the frequency of the masculine timeline that is defined by its state.

The amount of energy that is stored in the territory and the movement patterns that have evolved based on interactions specifically the family tree could either create more energy sources or result in depletion. with a decreasing probability of rejuvenation.

Suppose the new masculine has a collective frequency that describes the probability of energy consumption and territory expansion, the old masculine which is located at the origin " o " could divert energy and directional movement information based on his territory intent to continue or remove the frequency of the timeline. This occurs as a result of quantum entanglement between the instincts of the old and the new masculines.

Since the old masculine could change the state of his territory such that the movement of other individuals could controlled, the laws of continuity cannot be broken.

1.3 The original territory intent of the masculine

If the original intent of the masculine is to create various timelines or frequencies in his territory, observe the interaction of frequencies, and identify or create the frequencies that result in territory expansion periodically then the intents of any new masculines that are created from the original masculine's territory are quantum entangled to this original territory intent.

1.4 Expansion of the territory

The expansion of the territory occurs with the growth of each individual such that the energy that is being consumed in the circle of " o " will produce " k " new masculines in the territory (circle) of " o " such that the area of the circle of influence defined by each of the " k " masculines could be defined by Rk.

Each of the masculine " k " could have its own territory such that it serves as the energy source for the individual points in the territory (radius).

As each masculine has its own territory through which it serves as the energy

source for the movement of the remaining (n-k) individuals as their movement trajectory intersects with the area of each of the masculine.

As the number of masculines increases then eventually one or more of the masculine will have a territory or sphere that grows outside the area of the masculine defined by the origin o.

This then expands the area or sphere of influence of the masculine at origin " o " , because the movement that occurs outside the circle of influence with radius R could then be correlated to the movement that occurs within the radius.

2 The interaction time of the masculines

The interactions of the masculine could be described as the following on a day-to-day basis in the following ways :

n individuals, where x could be the random duration of the interactions.

If there are N masculines in the territory, then each of the masculine could borrow y % of the interaction time to declare intent to the individual in one way shape or form, specifically bringing the intent of the individual to the conscious awareness to the individual in the interaction.

This method of communication could be called intent communication, which could be done either verbally or non-verbally. The nonverbal form could take psychic communication where the intent of one individual could be transferred to another individual's consciousness by paying attention to the individual and the intent for prolonged periods of time. This could force the attention of the individual through actions repeated as a consequence of the attention maximization technique.

2.1 Uni-dimensional Perception

This form of perception results from the inability to shift consciousness from the bounded form of communication where an individual only observes the narrative from the individuals in his surroundings. This perception of an individual binds to the storyline (narrative regressed from the information shared in the surroundings) without observing the cause and effect from the projected intent and the actual intent of individuals.

To illustrate, if an individual is trying to engineer a perception of himself to the other individuals in the interaction, then the details that the individual brings to the other individuals in the interaction could be part of the engineering process.

2.2 The perception without assumptions

The objective reality which is the dimension of geometry where the location of individuals could be assumed to be interactions. An individual's time spread could be described as the split of interactions between various groups of people that lasts for a random duration x.

This perception does not allow for the assumption of projected intent because

the assumption would be that the duration of the interaction would be perceived or random depending on the intent of the individual, hence, it forms a deterministic boundary condition. The intent will be assumed to be precise with zero error.

2. The perception allows for the projected intent where any duration of time y % taken for projected intent which could be assumed to be deception. This allows the creation of probabilities of actual intent or projected intent based on further analysis of the details in the interaction.

2.3 Other forms of observations

The dimension of conscious intent - The conscious intent of the individual could be deduced by measuring the duration of time in which the individual projects intent (details that repeat with a frequency in similar or various other contexts)

The distribution could then be distributed as a probability of the intent being a projection of the true intent or genuine intent of the individual

There could also be a possibility where certain individuals could have higher conscious awareness, enough to perceive the true intent of other individuals by natural biological law that could be correlated in genetics.

2.4 The evolutionary process by perception maximization

If an individual is able to perceive all three modes of perception, then the conscious awareness of the individual could change the dimensionality of consciousness by altering the scale and dimension of observation in any interactions.

This forces the consciousness capacity to increase, thus resulting in more precise conscious control of the surroundings. The time spent by an individual would be altered based on other details, specifically the intent, the duration of the intent, and the individuals selected for the interaction for the intent.

3 The Intent- Time distribution

Let the animal be assumed to be the highest authority in the territory. The definition of authority could be described as the amount of conscious control the species has over the other species in the territory.

The individual entity of the species could be assumed to have conscious awareness to set conscious intents in the following core areas :

Survival intents

Nonsurvival intents

Reproductive intents

3.1 The balance

The above broad categories of intents could further be split under the following subcategories of intents based on the two categories defined below :

Purpose of the individual - (The Ecosystem creates the individual through the intents of the parents for a function built into the genetics)

The intent of the individual - (The individual creates his own intents for the surroundings)

The existance of the individual in the ecosystem has to be balanced with the following interaction.

The usefulness of the ecosystem to the individual

The usefulness of the individual to the ecosystem

3.2 Free will choice of intents

There are m possible intents of any individual, which is the genetically accumulated, inherited, and created along the way with free will for continued existence. Some examples are below.

1. Intent to build habitation

2. Intent to build territory

3. Intent to expand territory

4. Intent to survive

5. Intent to reproduce

6. Intent to protect resources of the territory/ protect

7. Intent to protect the resources

8. Intent to Conquest

9. Intent to create and balance

....

3.3 The grouping of intents

An individual could start an interaction with other individuals in the territory based on a primary intent for each interaction.

The intent setter of the interaction is the masculine of the interaction, and all the other individuals who align with the masculine bind their time and energy to the intent set by the masculine.

The energy of the intent is, therefore, the total number of individuals in the territory that have binded themselves to that intent.

3.4 The balance of all intents in the territory

Suppose there are " N " individuals in the territory and each has " m" conscious intents in the territory.

Let there be " n" masculines in the territory who are the individuals who have a set of " m " intents each and " X " number of individuals in the territory aligned with the intents of the masculine.

There could be (n) (X) (m) conscious intents floating or moving in the territory that is fueling the current trajectory for the collective intent for the territory.

Where the variables n,X,m could be distinct or intersecting in any permutation and combination possible depending on the interactions of the n masculines with each other.

3.5 The authority of the masculines to the ecosystem

The highest weighted conscious intents are the ones that are defined by the established masculines.

Masculinity is achieved locally on a predefined region of boundary or territory with a voluntary binding contract to drain the energy from the local territory in one way and form.

The process of energy draining could occur by the voluntary actions of the individuals in the local territory whose intents align with the masculine on a micro intent level such that the actions of the individual could be controlled consciously by the masculine for a few seconds to a few hours depending on the capability of the masculine.

Therefore, the subintents that are defined by the masculine require time and energy towards its completion from the individuals in the surrounding area.

The action of the energy-draining process from the masculine from his territory could be achieved by using deceptive engineering, perception engineering, etc. Any form of engineering to establish the social structure of the colony in this format would require an additional duration of time D units that could take from months to a few hundred years to establish the mirage.

3.6 The binding contract in the mirage

The aggressive set of consent required at each location or interaction could be defined by a set of actions that either resemble verbal or non-verbal consent.

The specific area or location for the binding contract has to be defined for a duration of time. Any contract signed with a verbal or nonverbal action will be valid for a duration time of time set by the masculine. The time and energy-draining process has to be explicitly defined in contracts with measurable metrics such as location, time or duration, or the number of individuals bound by the contract.

This process could be embedded into society as a social or economic norm based on the geographical area defined as the territory of the masculine.

3.7 The energy shared between the masculine and the feminine

Masculinity involves the usage of energy from the individuals in the area. Since the masculine controls the actions of the individuals, their movement could be controlled by the masculine. This forces the individuals to be in the orbit of the masculine and, thus, become feminine in nature. Therefore the movement of the feminine in the surrounding areas could become susceptible to conscious or unconscious control.

The masculine could use the feminine to observe the surroundings and perform actions through the feminine from a distance. The primary intent of the feminine becomes the primary intent of the masculine by natural law in the territory.

This natural process of intent distribution between the individuals in the ecosystem

3.8 The balance between the individual and the ecosystem

The impact of any specific individuals in the territory is always set by the hierarchy of masculines and could be the cause of any trajectory that is not favorable to a higher authority governing the territory.

The higher authority will then interact with the new feminines (current masculines causing the unfavorable trajectory) and reset the primary intent of the former masculines, thus changing the resultant outcome of the larger trajectory set by the masculines in the territory.

The authority could then identify to account for interaction rules such as the amount of free will that is distributed for an individual's survival, nonsurvival, and reproductive needs to ensure the movement towards the new trajectory defined by the authority.

The shift from the current trajectory to a new trajectory occurs by the individual change in behavior patterns or movement of individuals in the geographical locations of the territory.

The distribution of conscious and unconscious primary intent towards the movement of the individual in the trajectory is the sum of actions of either the primary intent of the individual or the masculine.

3.9 The Effect of Masculine Interaction in the Territory

The redistribution of the masculine authority in the ecosystem will alter the conscious awareness of the individuals in the population towards the intent of the current masculines and the new masculine.

Conscious awareness in the population will increase towards the conflict of intent between the masculines, which will be used to interact with the surroundings to create the new individual trajectory set by free will.

This interaction between the former and current masculines could force the objective truth in the territory, which could be hidden by the former masculines to achieve stability in the territory.

The objective truth for all " N " individuals in the territory that could stabilize the trajectory of all individuals in the trajectory could be the leadership structure and the intents of the leadership structure.

If the new masculine has a conscious intent to alter the trajectory, then the fastest time duration or interaction could establish the boundary conditions by engineering situations for the objective truth to be integrated into the collective perception.

3.10 The interruption of the Authority as a boundary condition for evolution

The objective reality has to be analyzed for conscious awareness that describes the movement of the individuals that is either stable or unstable, thus being a threat to the evolutionary process of consciousness.

The movement is described by the trajectories set by the masculine for the feminines in the territory. The masculine creates a hierarchical structure in the territory based on geographical locations to control the vicinity surrounding the masculine, which includes the movement of each individual in a specific boundary governed by the masculine.

3.11 The family tree of the masculines

The genetics of consciousness where the sustainability and the usefulness of each masculine family tree of consciousness are redefined at the evolutionary stages that occur between the relationship between a masculine family tree and the surroundings.

A similar structure is found in the feminine family trees, and the masculine family trees assign various roles and responsibilities based on their applications to the masculine. The masculine family tree ensures the balance of the territory requirement of each family tree, the primary intent of the feminine family tree, and the primary intent of the masculine for the feminine family trees. The balanced intents from three sources of hierarchy will define the boundary conditions for the stability of the leadership structure with regard to the desired movement for the trajectory set.

3.12 The ascension to masculinity

The laws of creation allow for ascension to increase conscious awareness; however, the rules to acquire them must be observed for continued sustainability.

The parasitic consumption of free will for the observation of a masculine intent implies the time is lost for the free will intent of the individual. Furthermore, it could disrupt the purpose of the family tree of the individual from the ecosystem if it is being controlled by the masculine and the goals don't align with the ecosystem.

Since the ecosystem outranks any individual family tree, native or foreign, the individuals, including the masculines are bound by the amount of time spent in the ecosystem.

The automatic residence status of any foreign entity in the territory after birth in the specific ecosystem implies the intents of the ecosystem are also embedded in the ecosystem.

3.13 The types of movement of the family tree structure

The movement of the family trees that are beneficial to the ecosystem.

The movement of the family trees that are not beneficial to the ecosystem

The movement of the family trees defines the founding structure of the timeline

in an ecosystem through forced evolution by the authority.

.....

3.14 Conscious intents defined by location-time

The masculine family trees that are strategically placed in each territory control the flow of conscious intents in each of the family trees in the territory of the masculines. The conscious intent could be traced through the individual and collective movement of individuals in the territory to fulfill their respective intents.

Each conscious intent that is defined by the masculine or the feminine could be described with a location, the duration that an individual spends time in that location, and the other individuals in the location.

Therefore, any intent could be defined as the following representation.

Intent A

Initiate interaction at location x for a duration of Y hours with " z " individuals

Relocate to location y either predetermined or acquired from the previous interaction

Initiate interaction at location p for a duration of Q hours with " r " individuals

Relocate to location L, either predetermined or acquired from the previous interaction

.....

Repeat till Intent A is completed or abandoned due to external resistance in interaction that arises from the conscious intents of the other individuals.

3.15 The imbalance of movement

Suppose the movement of intents in any defined territory has been imbalanced as a result of the local masculine in the territory. Then, the interaction with the authority skeleton crew will break the masculinity structure in the ecosystem to break the information flow from the masculine to the individuals in the

ecosystem to alter the collective movement.

The interaction of the new masculine in the territory will halt the movement patterns of the conscious intents in that interaction surrounding the old masculine is responsible for the unstable conscious intents in the ecosystem, which is being reflected in the movement of family trees in the ecosystem.

The resulting restructuring of the conscious intents in the defined boundary of the territory will create a new movement by raising the conscious awareness of the individual in the surroundings.

The conscious awareness of each individual will integrate the information about the interaction from the masculine prime and current masculine leadership, and the intent-time distribution of the territory could result in stochastic movement based on observation and the trial and error of interaction mechanism until the chaotic movements collectively interact with each other to stabilize the movement in the Ecosystem.

4 Rules of interaction time

Let an individual's life be defined as T years in the time dimension

Let an individual's life be defined as the following two core functions of consciousness

Observation

Interaction

4.1 Defining perception as a function of time

The perception of an individual is defined as the current set of time boundaries for the individuals in the surroundings.

Suppose an individual spends his entire life with three individuals on an island

To illustrate if individuals A, B C are the only three individuals in the surroundings, then,

Time spent with self or alone - x hours

Time spent with individual A - y hours

Time spent with individual B - z hours

Time spent with individual C - w hours

The individual's lifetime = T years could be split as follows :

x + y + z + w = T years

4.2 Interactions as the medium of perception exchange

The shared time between individuals serves as a communication pathway between individuals where information is exchanged. The shared time could be described as a physical boundary where the interaction occurs.

The perception is a function of the amount of time spent in interactions because of the several intersections of perceptions (opinions or accurate conscious

awareness) of other individuals with the following considerations.

The masculine perception in the interaction - The individual with the highest conscious awareness in the interaction who is capable of masking his intent or high probability of intent deception. This process of deception by the masculine requires the accurate prediction of the other individual's intent. If there are only three individuals, then it could either be A, B, or C.

2. The perception of individual A towards B

3. The perception of Individual B towards A

4. The perception of individual C towards A

. ..

4.3 Information stored in perception

The authority level of the ecosystem - On a conscious level with respect to survival and sexual instincts

2. The trust factor/deception factor - The utilization of deception in survival needs or non-survival needs, or both.

The interaction of the perceptions in interactions results in changes in the perception of each other. Thus, perception becomes a function of time, and as the interaction duration increases, more information is exchanged that either increases or decreases the above two factors.

4.4 The boundary of observation

When an individual is born at a time t = 0

The individual observes the individuals in their surroundings, specifically the parents. The boundaries for perception are defined by the intent of the parents with their time.

The Conscious intent of the parents is defined by the geometric actions defined over a period of time.

The boundary keys or the rules for interactions that is observed as intent from the parents towards the following groups :

Family

Friends

Coworker

...

The boundary keys define how an individual interacts with generalized clusters of individuals, and the individual observes the keys and integrates them into the interaction mechanism. Thus, the conscious intents of the parents towards various clusters of groups are transferred to the individual.

4.5 The interaction-specific keys

The authority level of the ecosystem - On a conscious level with respect to survival and sexual instincts

The trust factor/deception factor - The utilization of deception in survival needs or non-survival needs, or both.

The interaction-specific keys are defined by a range of time distribution such that the above two metrics of the individual are balanced to maximize the efficiency of information flow in the interaction.

The efficiency of the interaction is maximized when deception in the interaction is nonexistent. This is because deception requires time to organize, plan, and execute, which is a large portion of the interaction.

Therefore authenticity of the interaction has to be maximized to reduce time on deception.

4.6 The aggression interaction keys

One mode of interaction that is effective in interactions that have a high probability of deception is aggressive interaction. Aggression could take the following forms:

Challenging authority

Challenging trust factor

The perception of an individual could also be measured in aggression where the aggression levels of the individual could be rated based on the probability of an interaction turning aggressive as the result of the individual's boundary keys of interaction.

5 Interaction in the Ecosystem

Let the Ecosystem for any individual be defined by a defined boundary that could be observed from any point as the origin. (similar to a point in the middle of a circle)

Suppose the GPS coordinates of conscious entities could be plotted on a graph, and the scale of the graph could be adjusted such that it would be a dimensionally accurate replica of the movement of conscious entities.

This could be achieved by accurately tracking all the conscious entities in the immediate surroundings of the individual.

This pattern of relative movement where the collective coordinates of all the individuals form a pattern that could be analyzed for the nature of the collective movement.

To illustrate, an individual employed in an environment could be traced by collectively observing all the individuals in the environment and their interactions

5.1 The boundary conditions for location surveillance

The interaction could be defined by defining an area called personal space for an individual where all the individuals within a few meters of the individual could be defined as one of the boundary conditions. This could be defined as an intimate interaction

The second boundary condition could be defined as a general surrounding area where the individuals within the general space could be defined as a non-intimate interaction

The amount of time the individuals spend with the other individuals is relative, thus forming several iterations of interactions between the individuals in any area.

For example,

If individuals A, B, and C are interacting in the same house, then the plot of their collective movement in a 24-hour cycle could be analyzed, and the two kinds of interaction could be sorted

The amount of time spent between individual A and individual B in intimated interaction

The amount of time spent between individual A and individual B in non-intimate interaction

The amount of time spent between individual A and individual C in intimated interaction

The amount of time spent between individual C and individual B in non-intimate interaction

.....

The nature of the relationship between the individuals could then be analyzed with more observation data. The higher the number of interactions recorded, the higher the probability of estimating the nature of the interaction between the individuals between each other

5.2 The intent matrix of an interaction

For Individual A :

primary intent towards individual B

Projected intent towards individual B

.....

For Individual C :

primary intent towards individual A

Projected intent towards individual B

.....

The above matrix could be regressed by analyzing a large amount of observational data of any individual. Any source could be potentially used that tracks location in real-time such as a tablet, smartphone, etc.

5.3 The perception of movement

The science of movement could be described in the following formats :

The relative movement of conscious entities in the ecosystem in the first perspective The relative movement of conscious entities in the ecosystem in the third perspective The relative movement of conscious entities in the ecosystem on a 5D plane

The above movements could be compared with each other.

For example, if the GPS captures the movement of conscious entities in the ecosystem on a 5D plane, that could be similar to a graph on a 2D plane where the x-axis determines the coordinate (x, y, z) and the y-axis stores the time where the coordinate is observed.

The above movement could also be captured by a couple of CCTV cameras, and this would be a different perspective of the same movement above.

The above movement could also be observed and reported by eyewitnesses, and this would be a different perspective of the same movement above.

.....

Therefore, all the perceptions of the same movement could be used as training data to map various kinds of movement types that could take different shapes geometrically. However, with more observation data that has significantly more information than various kinds of movements, such as intimate interaction movements, non-intimate interaction movements such as platonic friendship, siblings, and relatives could be defined based on various parameters.

5.4 Mechanics of deducing intent

The method of sorting intimate or non-intimate interactions based on the defined boundary conditions above could be weaponized by deducing the intent matrix of any interaction group.

Suppose if an individual is identified as a target for a military class :

n - the number of individuals interacting with the individual is mapped after an observation of a few hours to months, depending on the purpose

After the movement of the individual is plotted on a graph with the movement of the other individual, the nature of the relationship between the individual

and the "n" other individual could be deduced.

5.5 The intent matrix

Each individual has a primary intent toward each of the individuals in the interaction

Each individual has a projected intent towards each of the other individuals in the interaction

5.6 Deception

The deception of intent is a process that is part of the evolutionary chain of conscious intent however, the rules of deception in interactions have a defined boundary condition beyond which the genetic trait becomes parasitic.

5.7 Time Morality

Since conscious interactions require time from each individual, only one of the primary intents could take priority as the purpose of the interaction.

Suppose if n individuals are interacting; then one individual has to lead with the intent of the interaction, and (n-1) individuals will follow the intent.

Therefore, (n-1) individuals are donating time to the intent of the single individual

For any one individual at any given time is interacting with x interactions.

Some of the intents could be initiated as the masculine self or donating time as the feminine to the interaction based on the intent matrix.

Therefore, the balance of either taking time for an individual from the collective or an individual donating time to the collective will be met over a duration of time, which could be random or deterministic.

Thus, learning the rules of interactions to either consciously progress in the evolutionary scale indefinitely or to face the consequences of interaction laws used or assumed.

6 The analytics of grouping in an ecosystem

Let an individual be part of the Earth Territory.

Let there be N individuals in the Earth Territory

An individual interacts with "n "other individuals during the course of his lifetime.

The multiverse or the timelines of the individual could be described as the following

The representation of all possible future trajectories for an individual could be generalized to a key set of data points for representation.

The breakdown of the complex components could be dimensionally reduced to the " m " conscious intents that an individual has per lifetime.

Let each individual have "m" intents per lifetime

The probable realities of any individual is made up of (n+1) individuals, where n is the number of individuals that interact with him.

The multiverse of the individual is therefore finite and always originates from the (n+1) individuals collectively.

Therefore, the multiverse for any individual could be defined as [(n+1) *m] finite possibilities.

Therefore,

The probable realities of any individual are directly proportional to "n" and "m" . The breakdown of the variables :

n: number of individuals that the target individual has interacted with

m: The number of intents that each individual carries

Both the above variables are dependent on each individual independently. This essentially implies that the following metrics become relevant:

The authority of the individual in the territory

The conscious awareness about his surroundings (The amount of accurate information he has about his surroundings)

Consciousness capacity

Therefore, the objective reality that is presented at each instant of current time t is the resultant of all the intents that have aligned. The alignment of intents occurs according to natural law based on the above three metrics mentioned above.

The multiverse becomes stationary at each moment in time, which is the manifestation of all the intents based on their weight contribution based on each specific individual who is the source of the intent.

6.1 The interaction of the individual in society

A society is defined as a structure where a grouping of individuals occurs based on an intent.

Each individual could be part of " x " groups defined by an intent during his intent.

Each individual is part of "x" different groups that may or may not intersect based on the intent.

Each of these " x" groups could be assumed to function independently . The function of the group is to " share time " such that the individuals in the group use their energy to perform a set of tasks required to fulfill the intent.

"x" could be in the order of millions. If there is no deception of intent in the formation of the group, then " x = m ", however, there is no guarantee that the intent is authentically declared. It would be possible to define actions strategically such that the intent of the group remains masked. The definition of a group could be defined simply as any interaction that an individual experiences, he shares his time with a single or multiple individuals. In the age of technology, interaction could be achieved instantly, where the attention of the individual could be dragged into any interaction at a moment's notice.

The behavior of the individual changes according to the collective perception of interaction or group he is a part of. Under each group, the individual who has the ability to drain the attention of all the individuals at a consistent rate would be defined as the masculine of the interaction.

However, deception of intent could also be used to drain attention of the individuals in the surroundings.

There could also be other limits from each interactions which are designed according to several masculine traits from each group interacting such as :

The amount of deception in the interaction. If the foundation is based on deception, then the information flow in the interaction becomes harder to identify as accurate or inaccurate. Therefore, the initiators of any intent are the prime suspects for intent manipulation, which has to be countered with transparency with ascending leadership (the masculinity of the group)

Perception limits of any individual in the interaction as a result of the collective umbrella perception of each group. The collective umbrella perception describes all the parameters that justify the creation and the execution of the intent.

The umbrella (projected) perception is therefore the stimulus that leads to the creation of an interaction with an increasing number of individuals .

If deception is used to the formation of the group or interaction, it occurs in the perception engineering stage for the target individuals.

Situational engineering, deception engineering, perception engineering, attention engineering, and several other interplanetary sciences are used to create a perception such that the desired number of individuals could join the interaction and perform the tasks necessary.

In a broader context, the group or interaction could also be described as the employment or education system, an interaction is forced upon the individual through out the course of most of his life.

6.2 The creation of intents in the society

Each intent could be generated at any moment of time.

There could be "z" different intents being generated per day, where z could be large beyond calculable.

6.3 Engineering intent as a consciousness weapon

Intent could also be represented as a response to external stimuli.

If a species observed another species on another planet and analyzed its behavior through its movements or coordinates through time, and plotted it on a graph to understand its behavior.

The measures that could be used as input and put as a stimulus are attention, distraction.

If the attention distraction weapon is initiated, then the target individual should get his attention distracted for a duration of X seconds.

This technology could be described as a consciousness weapon.

7 The Mechanics of conscious trajectory

7.1 Defining life with consciousness

Let there be an entity with the possibility of separating itself into N different versions of the entity, which could be a fragmented or the whole entity. The entity could even create more variations of itself by interacting with N different versions of itself.

The entity could perform two functions with different variations of itself :

Observe

Interact

Consciousness could be defined as a boundary description of any one variation of the entity with the rest of the variations as a whole. The boundary contains information from observation (conscious awareness of the surroundings), and learned interaction rules to plot forward moment based on information acquired from observation.

Each variation of the entity created either by itself as a whole, a fragmented version of itself, or variations arising from different variations, either competing, collaborating, or destroying with other variations

7.2 Defining life as a straight line in the time dimension

Let the life of an individual be defined as a straight line that starts and ends at a time :

t = 0 , year x

t = T, year (x+ T)

Therefore, the life of the individual is a straight line when represented by time only.

Let the consciousness of the individual be defined as the entity that traverses through time in a straight line starting from birth year to the death year.

The consciousness of the individual at any given instant of time could observe or interact with other consciousness in the surroundings.

7.3 The observation and interaction

Lifespan of the individual = T years

Intent estimated from lifespan = X (depending on the individual consciousness actions)

X is the intent of an individual that could be summarized after the completion of a lifetime.

The intent could be deterministically set by the individual moving forward with conscious trajectory plotting in every aspect of life, or the intent could be the resultant of several intents of the individual that have accumulated during the individual's lifetime.

Therefore, the intent X could be deterministic, random or a weighted mixture of the two based on free will choices (embedded in the boundary of the individual consciousness)

7.4 Discretizing individual consciousness

An individual consciousness is a unique entity that is defined by its observation and interaction capabilities.

The interaction of the individual consciousness with other conscious entities could be simplified as the following :

7.5 The flow of consciousness creation

One consciousness TO Splitting into N variations TO Creation of more variations by observation and interactions TO Splitting and/or merging into M variations TO Creation of more variations by observation and interactions TO .....

7.5.1 Identifying an individual consciousness

If any one individual consciousness is observed for its interaction with other conscious entities, this could be achieved by separating consciousness into the following :

One consciousness (Everything in the ecosystem) = The individual consciousness + The remaining components of consciousness (Consciousness as a whole without this individual consciousness)

Therefore, the above breakdown creates three conscious entities that could observe and interact with each other.

One consciousness (whole) - Has all the information

Individual consciousness (one segment) - Has a limited amount of information

Other consciousness excluding the selected Individual consciousness (other segments) - Has less information than one consciousness and more information than individual consciousness.

7.6 Consciousness and the timeline trajectory

For any individual consciousness, the lifetime is defined by three components of the consciousness fragments :

Whole

One segment

Other segments

Whole consciousness = one segment of consciousness + other segments of consciousness

Three components of consciousness are interacting simultaneously as the individual traverses through his lifetime.

7.7 The direction of time

Since the individual consciousness traverses through time in the forward direction, the decision making process for the individual occurs in the forward direction of time by collecting information till the current moment.

The whole or the one consciousness would not be bound by any limits for interaction as it would have all the available information for decision making.

The other segments, excluding the individual conciousness, form the platform with which the individual interacts to continue the trajectory of consciousness movement.

Suppose the other segments or the whole consciousness wanted to interact with the individual at a point of time, the interaction would occur by including information from the future probable trajectories unavailable to the individual.

For any larger consciousness that interacts with an individual, it could plot trajectories for interaction backwards in time, however the individual consciousness could only perceive it moving forward in time.

Therefore, any interaction consciously plotted by the whole consciousness or the other segments becomes deterministic for the individual consciousness.

7.8 Consciousness communication channels

The Individual consciousness uses a psychic link between the individual consciousness and other variations of consciousness.

The information transfer that occurs is made available through a link or a pipeline that instantly connects conscious entities who are willing to communicate.

The pipeline is present in every individual and can be accessed by using the attention vector of the individual towards this channel. The attention vector of the individual consciousness could be directed either internally and externally to the individual, and it has to be directed towards the location of the communication channel by visualization.

7.9 Restrictions to the communication channel

1.The awareness of the channel

2. The calling card of other conscious entities that the individual is trying to communicate

3. The number of dimensions this communication channel connects.

The higher the connections that an individual could make with his consciousness, the higher the information he could acquire from the other fragments of consciousness.

7.10 Trajectory setting using information from consciousness communication channels

If every individual consciousness is individually directed for its trajectory with information from other fragments of consciousness, then the collective could be directed towards a particular trajectory by any larger consciousness (other fragments) observing the collective trajectory.

Such interaction will increase concious awareness of the individual conscious awareness as a natural consequence of conscious entities that could have information from the future trajectory or timeline.

To illustrate, suppose if any individual consciousness is interacting in a territory, the consciousness of the territory as a whole could decide to establish a consciousness communication channel with the individual to divert his movement in the territory according to the territory's intent. The territory could provide information in an infinite number of dimensions based on the need. The information is data that is acquired by observing various elements in the territory, where the dimensions could be any, such as information about the infinitely small or the infinitely large change that is influencing the territory. Such interactions could occur when there is an imbalance created in the territory in one way, shape or form and is always initiated by the consciousness with the highest capacity of consciousness.

7.11 The authority of individual consciousness entities

The laws of creation enable the continuous flow of conscious creation and several conscious entities could be offered dominion for observation and interaction to maintain the laws of creation.

The dominion of the individual is defined by the ability of the information to extract information from the whole consciousness in that particular dimension.

To illustrate, an individual could be granted dominion over observing a change on a microscopic level in the territory and therefore could be capable of determining cause and effect at a microscopic scale.

The leadership could spread across many dimensions depending on the territory. Domains could further be created and analyzed, or as a permutation and combination of dimensions.

7.12 Functions of authority for the individual consciousness

The creation of leadership for the expansion of any specified Territory (Earth, for example), could be to accomplish the following functions :

Realignment of variables to start generating creative potential

Redistribution of the population cluster based on needs

Realignment of territory laws with a new decentralized version

Realignment of territory laws, which includes information on dimensional laws

Introduction or alignment of time morality laws to ensure free will and energy distribution both geographically and dimensionally.

7.13 Inter-dimensional conscious interactions

The mutual symbiosis between fifth-dimensional entities and three-dimensional entities will be aligned to ensure the balance of the ecosystem.

Suppose if the fifth dimensional entities are using the individual conscious entities as a food/energy source, then the laws of interaction should be aligned with equilibrium to benefit both parties for coexistence.

7.14 Relationship between consciousness and intent

Defining one consciousness as a collection of infinitely possible intents. Each intent could be defined as a consciousness that is designed to exist to fulfill the intent.

Initial bonus condition for consciousness for the expansion:

Infinite intents break off in all directions, creating N different variations of conscious intents.

The movement of intents begins in all directions, and will eventually collaborate or compete with other intents to expand creation, more intents thus creating

more consciousness to fulfill that intent.

The resulting intent that emerges from the collaboration or completion will bind the participating intents into a specific movement that is directional at every present movement.

The movement of each independent intent or a collection of intents will reach a stable moment trajectory that will either create, destroy, or interact with other intents.

Some intents break off into smaller intents or merge into other intents and continue their motion, expanding into more intents or consciousness, going through a sequence of collaborations and completions.

7.15 Alignment of intents or consciousness

At every point in an interaction, when a conscious intent, which is collaborating or competing with other intents, occurs, results in one or more of the following from conscious entities. The alignments restrict the movement of intentions or consciousness according to the trajectory defined by the higher capacity consciousness.

Natural alignment of interaction events that will result in stable movement of intents that will continue the flow of creation.

Negotiated the Alignment of intents to alter the direction and velocity of movement of the intents. This could occur depending on the motivation of the higher capacity consciousness or intent.

Death of intents - Intents that don't align, or rather projected to have no pathway for movement, collapse or die.

7.16 Mass of Consciousness

Suppose that each intent is assumed to have a point mass in the dimension of intent. Any interaction of any intent with other intent could result in merging or coexistence of intents. In such scenarios, the mass of the consciousness fueled by the addition of each intent will grow. The higher the mass of the intent, by aligning with other intents, the higher amount of energy it could use for its forward trajectory.

Therefore, accumulation of mass occurs for conscious entities that maintain

their intent alignment with the surroundings with equilibrium.

The intent or consciousness remains active until the intent is completed.

The trajectory of the intent could be altered by an external force, such as :

The reason for the intent no longer exists and the consciousness disappears as it has no intent to fulfill.

The trajectory or pathways that allow for the movement of the intent get shorter and more compromised as a result of other opposing intents in the ecosystem.

When the trajectory pathway decided by the intent reduces to zero, the intent which was originally planned and keeps the consciousness alive indefinitely dissolves.

The consciousness could displace itself even after death from the original intent of creation, the consciousness is kept active by displacing itself between nodes of all the individuals who had been influenced or aligned to the original intent.

The consciousness will eventually locate itself into a static vessel and stabilize permanently by merging the intents into one of its nodes. The individuals or nodes who had been bound to a particular movement by the original intent serve as computational nodes for the consciousness to use and make decisions in the ecosystem.

The consciousness will have the ability to relocate itself into any of its nodes, it will remain in the node that has the maximum amount of interaction capacity. This is usually decided by the authority and skills of the individual who is executing the intent.

Therefore, the evolution of any consciousness is the movement of conscious intents. The intents are uncountable and infinite because of the constant generation of more intents.

The intent to balance accumulation, collaborating, and competition of intents arises from the founding intent of creation set by the one consciousness.

The movement of intents that arises from interaction with other intents could take a fractal shape that represents the growth of intents.

Creation of conscious life could be described as the infinite fractal. Any variation in the fractal shape will require intervention from the primary intent of the one consciousness to maintain the flow of conscious creation in harmony.

7.17 The laws of creation applied to intent

If an intent existed for a duration of T units, then the collective perception of all the individuals with that intent could become independent and become an independent consciousness with the ability to plot its own future trajectory.

The consciousness will remain active until the intent still exists in at least one of its aligned nodes.

The newly created consciousness will have survival instincts as the primary instinct and non-survival instincts based on the personality or consciousness that created that intent.

8 The intent control in the territory

Let there be N individuals in the territory

Let each individual have " m" intents at any given time t

8.1 The source of the intent pool

The source of the "m" intents could either be :

Genetic tree pool

Free will choice based on the available options in the surroundings, either to observe or interact with the attention vector of the individual

Other - Any external force engineering the intent by creating an illusion

The types of intents

Survival instinct

Sexual instinct

Non-survival instinct

8.2 Engineering intents

Survival intents could be engineered in the long and short term over the lifetime period through perception engineering

Non-survival intents could be regressed based on the user's available data based on his past repetitive movements or non-repetitive moments. The metrics location, the individuals in the area, and the exit location trajectories to the next interaction in the timeline.

Sexual instincts could be engineered by triggers placed in each location or interaction. The repetitive actions of a mating call sent out to the surroundings is a natural process; however, planting specific mating triggers through the surroundings triggers the biological sexual instinct. This could be weaponized to weaken the aggression levels in the individuals by constantly placing the individual in a triggered state of fighting the instinct to observe the mating call.

8.3 The correlation between perception and intent

Since Intent could be engineered towards broad categories based on the requirement in his surrounding area. If the locations of individuals are identified relative to each other, then the intent for any individual could be engineered based on the requirement in the ecosystem

The engineering process where the intent is engineered or regressed by an external force could be the following:

The ecosystem, through the laws of continuity

The governing authority in the ecosystem uses technology or brute force.

Intent-based on needs could be described as the movement of the individual in a specific trajectory in the ecosystem. The movement is described as the specific geometric actions where the individual has an interaction either by himself or with other individuals

Therefore, the intent could then be described as the collection of locations and the time spent in each location. Therefore, the intent ends when the destination and the time spent in the location ends.

8.4 Intent engineering

The current state

location

number of individuals in the surroundings - n

current number of interactions currently ongoing at the current time t - x

Let z be the number of steps to be engineered to go from the current state to the target state. The more steps that are required, the more time and energy is required.

The target state

location

number of individuals in the surroundings - m

current number of interactions currently ongoing at the current time t - y

8.5 The perception of the movement driven by the intent

The lifetime of an individual is, therefore, a collection of discretized points "z" or locations where interactions occur from one current state to the target state.

The perception of the movement could be defined as "m" possibilities, where m is the number of individuals observing the movement, including the individual himself.

8.6 The timeline based on intent

The timeline of any individual intersects with the timelines of other individuals through interactions that occur at various locations for a duration.

The timeline of any individual at any time t could then be described based on the number of interactions that are directing intent toward the individual. The intent is the information flow that is flowing from the masculine in the territory or ecosystem.

Therefore, the " m" intents of the individual are driving the purpose of existence for any individual.

If the "m" intents could be engineered by controlling the interactions or, specifically, the locations of the individuals, then the probability of regressing the timeline of the individual is maximized.

Consciousness evolution occurs in the timeline where the observation of the individual and his surroundings occurs to understand the rules of interaction to retain territory integrity in the short and long term to maintain balance in the ecosystem.

9 Conscious intent as the objective reality

Let there be consciousness defined as unity.

The process of being conscious is defined as the ability to observe and interact.

The interaction and observation could occur within itself

Therefore the unity of consciousness could observe itself by imagining N different lenses or variations of itself.

9.1 Independence from unity

Suppose each variation of the imagined lens becomes an independent entity to imagine a perception where the origin of the perception is hidden.

The perception could be self-imagined or imagined by another.

Therefore in reality there are N different lenses that may or may not interact based on an intent.

9.2 Interaction of conscious entities

If the independent entities started interacting with themselves and created more trajectories or lenses to observe, then this would create a continuous movement of conscious creations.

Therefore if there are N individuals in the population cluster, then there are M perceptions that continuously originate from N individual conscious independent entities.

The perception of each conscious being changed when it interacts with other conscious beings because there is always an intent for each interaction.

Since the interaction involves one or more multiple individuals the intent would be interpreted by each individual perception independently.

9.3 Growing perceptions or conscious entities

If the geometric form of these points of consciousness could be observed in a simulation then the conscious interaction could be simulated by the random variable " d " which is representative of length or time.

If conscious interactions are assumed to be deterministic for consciousness matter in this case represented by a point.

If fractals formed by the collective movement of these points represent the continuous flow of conscious life, then the arrangement of fractals could occur consciously by a consciousness that communicates via observation of change in geometry over time rather than perceptions.

9.4 The objective/perception of the higher dimensional beings

The higher dimensional beings could perceive the change in geometry over time where the scale of the observation could be specified via a boundary such as Earth Territory.

The movement of the higher dimensional beings which is purely geometrical in nature to their perception could be represented via equations or graphics.

For the higher dimensional beings, they could observe Earth's world similar to a 2D graph of a digital model, however, they could interact with the graph in real time. The implication is that they could interact with Earth's territory at a microscopic level and/or cosmic level simultaneously.

9.5 The interaction timing

The interaction of the higher dimensional beings could occur in real time where they would plot trajectories by observing all the variations of movement possible at any current moment through geometric arrangements.

Therefore the objective reality is continuous interactions of perceptions that originate from each individual consciousness.

9.6 The flow of continuity of geometry

The interactions create more trajectories or end the trajectories.

Suppose free will of the collective conscious matter on Earth Territory could be observed through the geometric change in the territory, then interaction for the higher dimensional beings could occur at any scale.

The possibilities for interaction are :

1. The movement of the collective conscious matter becomes chaotic and will need to be reordered with force The interruption of the creation of specific trajectories or geometric patterns that stagnates the flow of creation

2. Observation of consciousness as geometric particles

3. Suppose the evolving geometry on Earth's territory could be observed as a large collection of consciousness matter that is interacting with each other at an unimaginable scale but could be represented as the fractal of groups that groups.

Conscious Matter Group A

Conscious matter group B

....

There could be infinite open and closed loops of interactions between consciousness matter groups that could be observed geometrically in a dimension that could be perceived by the higher dimensional beings.

The growth or creation of more consciousness matter could be observed by the manifestation of geometry that expands in every trajectory possible and perceivable. Therefore this harmony in geometry could be observed by the higher dimensional beings through their perception.

10 Measuring intent as a force in space-time

Suppose a point consciousness has a radius of consciousness " r " such that the area of its awareness could be assumed to be territory.

The point could exert a force anywhere in the area of its awareness however, the effect that it is having is introducing information within that area. The information could include directives such as excreting a specific kind of force on any events that have been defined with that information.

The force that is exerted could be assumed to be a conscious intent that is defined by information. This process creates a cause-and-effect reaction from other point consciousness.

10.1 The Surroundings

If " n " individuals are assumed to be in the defined area " A ", then the effect does this conscious intent have on the " n " individuals who are also interacting with the environment in the same manner.

This process could be a force similar to an inertial force from an opposing conscious intent. If this is assumed to be a mathematical probability estimate for the masculine, this could indicate the force that is acting in the present movement.

The collective conscious intent of " n " such particles on any other conscious intent that is applied by force could interact in the subconscious information field.

The interaction is limited to the surroundings of the point consciousness that is altering the current movement vectors in the subconscious information matrix.

The interaction could be observed as an opposing force that is applied through any random individual point consciousness in the surroundings, depending on the interaction.

Each force or conscious intent acts as a driving force with various points of origin or frequencies

In real-time, if such conscious intents could be assumed to be of various frequencies, then any territory that was built over a conscious intent with a vision could lay the foundation for the changes in the territory.

Each conscious intent that is built over the territory intent is a web of tangled conscious intent that either collaborates or competes in the tangled web of

conscious intents in the subconsciousness information flow field.

10.2 The objective reality

An individual whose movement in objective reality could be described as the representation of movement that is the superposed movement vector of various hypothetical timelines or conscious intents that are being entertained by the population. The term entertainment in this context refers to the diversion of energy from an individual's time and energy through his attention vector. The specific amount of energy that he diverts his attention and the amount of force to draw that timeline grows.

The observation of these conscious intents could be described as the driving motivation factor for the individuals that have a hierarchy that could be described as " m " intents in any defined boundary. The masculines in the territory are then directing the movement of the other conscious intent, similar to the one defined by conscious intent defined for the territory.

The balance of intents that is required from the " n " intents in the family tree and the " m " intents in the territory occurs through the flow of information that occurs in the territory of movement of each individual.

11 Intent and perception

The perception function of consciousness P(t) = Function of the attention vector A

The attention vector has magnitude and direction at any given point in time

The perception function is a function of scale and dimension of observation. (In other words of location).

For simplicity, the perception could be assumed to observe and interact within the limit of that boundary.

The boundary therefore holds information that is always finite because once the boundary is set for observation, the information that could be absorbed becomes finite.

Similar to how an infinite set of possibilities converges to a deterministic trajectory of movement which is mathematically calculated to be close to the principle of least action. The minimization of energy and work could be applied in several dimensions of observations such as mass, energy, and information that could be conserved through equations.

Mass = Energy = Information

The equivalence could be mathematically approximated to observe the objective reality by finding the right dimension (combination or sequence of variables) through which it could be expressed such it could be useful to increase conscious awareness of the species.

The attention vector of consciousness at any level is always pointing at a direction or location. The location is the change in Earth's territory with respect to a dynamic or static observer.

Therefore it's a function of the observer's period/duration of existence

The period or duration or length is a function of the overall intent.

Therefore intent is a sequence of information that is compiled and stored in a particular sequence

11.1 Illustration

The ability to decode information from one boundary to another such as:

A man observing a set of atoms in movement.

The atoms observing the observer

While the conscious communication between the two depends on a technological translation, the intent communication through the information field could result in the following:

Intent alignment

Intent conflict

Intent negation

The movement could be the fluctuations of locations from one instant to the next although it may not be observable but could be deduced to determine which dimension is actually the attention vector to control its movement.

The movement control is essentially a language that is communicated by the subconscious information field that encloses the entire spacetime structure.

The entire movement structure from the movement of the black holes, planets, species, etc could be occurring as a result of communication with the information field that could be flowing through like a current that should resemble movement instinct.

The instinct in general refers to a course of action, especially the attention vector such that the movement of the individual which could be altered by the change in perception.

12 Time and Perception

An individual has current possible perceptions at any given point in time.

Perception of the self - X

Perception of the surroundings (including other individuals) - Y

12.1 Location of the individual

Time stamps could record the objective movement/displacement of the individual's location through time. Therefore, at various time stamps, such as

t = 0, home

t = T, office

....

The individual's location at any point in time could be known, and it is assumed to be the only known and accurate trajectory of the individual. Therefore, it is assumed to be the objective reality.

However, the individual's perception at a point in time, specifically X and Y, cannot be known because of the information limit obtainable.

12.2 Fragmenting the individual perception

The self plus the surroundings is the whole. A perception could be attached to any fragmented portion of the surroundings.

The perceptions X and Y are then defined for each interaction that the individual has over his lifetime of T years.

One lifetime of T years is a collection of N interactions of varying durations. Therefore, if an individual observes his surroundings without interacting, then each interaction of varying length is the intent for the duration of the interaction.

Therefore, collecting intents from each interaction duration over a lifetime will provide the collective intent for a lifetime, which could be defined as the lifetime intent.

12.3 The subjective element of perception

Since perception is subjective, it could be as unique as a fingerprint. The problem arises when the individual's responses do not match the collective perception of the surroundings.

All perception is a function of time, and perception towards the interpretation of mental illness, especially for a disease like the following, should be reexamined for clarity in terms of self and the surroundings.

The perception between two individuals becomes more unique when they spend more time together individually or collectively (of the same tribe or culture), and any behavior patterns that are associated with the following are time-intent dependent, subjective, and occasionally caused by external forces in one way, shape, or form.

Since perception is essentially creating a boundary between the self and the surroundings, the following diseases should be reevaluated in the context of conscious perception. Conscious perception is defined by learning to define the scale and dimension of observation.

12.4 Perception Analysis

When the individual perceives his surroundings, the expected perception is also the collective perception, which is the result of each perception in the collective.

Therefore, all perception is a function of time, and to change any perception, the following general steps are usually prescribed:

Observe perception of the self X at time t = o Observe perception of the surroundings Y at time t = o Identify individuals that are contributing to X and Y. Access the cause-and-effect relationship between individuals and X and Y.

Performing a set of confronting actions(pills, therapy, etc.)over a duration of T units (weeks, months, years)

Re-observe perception of the self and the surroundings Y at time t = D units

12.5 Change of Perception

The entire process of perception analysis is a game of changing perceptions. While changes in perceptions occur almost every day regarding various events or individuals, the following have to be evaluated:

Purpose: T+D units of time are spent on changing perceptions as a mental illness management mechanism.

Morality: If (T+D) units of time are spent on altering perceptions as a cure for perception mismatches, then the free will violation definition of morality has to be re-examined.

This is because if any individual perceives X and wants to change it to Y, even if it is voluntary, minimizing (T + D) units of time would provide the best solution to change perception as soon as possible.

12.6 The best solution

The best solution would then be to evaluate whether changing one's perception of oneself or one's surroundings is necessary for non-survival reasons if one's perception of any individual changes constantly as a function of time anyway.

A betrayal changes the perception of a friendship or a bad score on an employment review alters the perception of the self.

Forced external perception changes only occur if the perception of the self is dependent on the perception of the surroundings, thus binding the perception at each interaction one after the other.

13 Deception engineering

Let an individual have an intent at time t = 0

Let the intent be completed at time t = T units

Therefore, the amount of time for the intent completion = T units

Let the method of intent execution be defined as the process of communication. Human beings communicate with each other for a duration of T units on any given day.

Therefore, for any individual A, the 24-hour day cycle is split as follows:

Communication with individual B - 3 hours - intent - companionship

Communication with individual C - 3 hours - intent - employment

...

13.1 Introducing the Deception variable - an amount of time d units

Let the serpent variable be defined as an evolutionary strategy in which deception is a way of life for certain living organisms in an ecosystem. However, if such an ecosystem evolved enough to communicate with each other with either :

Verbal communication

Non-verbal communication

However, this creates a dual trajectory for any individual's intent. The human consciousness has an immune response to this which is known as suspicion.

If honest communication without deception took only T units, then two new variables are introduced into human communication.

Suspicion time - The amount of time an individual spends being suspicious about another individual - S units

Deception time - The amount of time an individual spends deceiving another individual + The amount of time an individual spends being deceived - D units

The halt in current productivity in human progress is because (D + S) units

of time per individual per day is being wasted mostly by opportunistic people trying to plot a life trajectory without understanding the laws of morality or the laws of the surroundings, which are the rules to plot trajectories.

13.2 The rules for trajectories

Observe the self - X units of time

Observe the surroundings - Y units of time

Interact with the self ...

Interact with the surroundings ...
Observe and interact with the surroundings so that the flow of creation is preserved and enforced in the surroundings.

The process could ensured with the free will - time observation in the self and surroundings.

Then correlate the following

Time spent in comfort / Discomfort - P units

Time spent violating/respecting the free will of individuals in the surroundings - Q units

The correlation between 1 and 2 is the delay factor between cause and effect—O units of time that is the delay between the action and reaction of intent, also commonly called karma, the binding law of time between an individual and his surroundings.

The purpose of the natural law of time or karma is to ensure that the interaction that occurs between individuals is maintained in accordance with free will equilibrium.

This guarantees the destruction of any single trajectory after choosing to become parasitic and consequently destroying the ecosystem.

14 Illusion of perception

At any given point in time "t", an individual from any species could be represented by its family tree.

The family tree could be illustrated as the genetic material of consciousness (or a soul that is part of a network of continuity in the flow of time. In this case, time could be represented as a linear line of length = T units.

Each point on this line has continuity to the genetic material of consciousness, and the capacity of consciousness could be described as the ability to observe the self and surroundings through a lens. This lens allows the observer to analyze their surroundings by every external and internal force acting on the surroundings.

Since life could exist potentially in any complex combination of consciousness and genetic material that could be from M dimensions (or M-dimensional beings).

14.1 Earth perception

To illustrate the average homo sapiens in space-time is a conscious being consciously observing three-dimensional bodies moving in the dimension of time.

These conscious observations in 3D or (X, Y, Z) format flowing through time could be extended to the evolutionary pathways of consciousness as the following

Consciousness evolution or the ascension process in the evolution of life varies with the observation capacity such as:

stage 2 (X Y Z) - Beings capable of observing space-time from within (three-dimensional perception where the change is occurring in the time dimension)

stage 3 (X Y Z t) - Beings are capable of observing space-time from within, from outside space-time. These beings could be the fifth-dimensional perception capable of being

stage N (X T Z t.....N) - Beings capable of observing space-time from N different continuity of any point consciousness.

14.2 Interaction between multi-dimensional beings

Trade of three-dimensional beings by the fifth-dimensional beings for time and energy.

14.2.1 Illustration

Having P number choices in the daily life of an individual to control his location trajectory. If the definition of free will is limited to moving around in any desired location at any given time that could be represented on a fifth-dimensional plane by the term (X Y Z t)

A three-dimensional individual could move around in any number of random ways with free will however if the free will rule is broken beyond a certain degree by higher dimension beings, the location pathways of the entire population cluster could be traced.

This collective movement tracing of the three-dimensional beings where Time T units and Energy E units are used to perform a set of tasks by fifth-dimensional perception capable beings.

14.3 Conscious awareness

If every individual in any population cluster could be sorted with the consciousness capacity of the cluster then:

Let there be N individuals

Let there be M three-dimensional perception conscious beings

Leadership is defined by the consciousness capacity - the ability to identify, sort, and identify illusions of perceptions.

If deception is used then the leadership is either

Collaborative class - usually lower conscious beings posing as higher conscious beings using manipulation or deception

Intermediary class - higher conscious beings who are provided status as lower conscious beings in the ecosystem using deception or manipulation to control the power, and reproduction status of the individual. However, this condition of illusion is management (1 individual to control 300-400 individuals) resource-exhaustive to control the intermediary class.

14.3.1 Higher order beings

Let there be (N - M) fifth dimensional perception conscious beings

Since the fifth-dimensional beings have higher-order information in space-time, engineering the entire population cluster by sorting them and identifying their intents could be possible by higher-order beings as the number of dimensions increases.

Military capable class - Intermediary class of people in the United Earth Empire heavily surrounded by individuals under covert perception control - This is because in any territory or land, the military class is genetically connected to the land and controls the collective trajectory of the land- Resource exhaustive operation for the fifth-dimensional beings unless they design Tech to conduct the constant surveillance to control individuals.

Collaborate class - deception commonality - beta individuals gaining alpha status in the system by collaborating to

A. Aid in the agenda of the fifth-dimensional beings

B. Controlling the Military class to keep their perception of the self as low as possible. This allows for keeping the immune system of the ecosystem from becoming active in case of free will violation and consequently obstructing the flow of creation.

14.4 Perception control

If the self-perception of any individual could be engineered to illustrate the lack of control in the surroundings, then individuals who might often resist the violation of free will could be metaphorically jailed.

14.4.1 Control Strategy

Control the military class from birth - Constantly introduce events to reinforce the perception of the lack of control in the surroundings

Eradicate the military class reputation by rapidly altering the perception of

the individual in the surroundings if this brut force control cannot be maintained.

Eradicate military class by forced individual or mass extermination.

Rapidly steer the intermediary class which performs most of the labor by extending time and energy to the goals of the leadership. This could be achieved by rapidly acquiring industries to alter perceptions about individuals or events using the flow of information.

Maintain authoritarian government by the fifth-dimensional capable leadership class while presenting the illusion of democracy. Therefore democracy could be an engineered tool to remove the perception of the authoritarian government to remove the collective attention vector away from genuine leadership.

14.4.2 Deception of governance projection

If the authoritarian government was a decentralized region with full sovereignty but united on a planetary scale based on the laws of morality or the laws of the surroundings - free will - time correlations . There would not be any need to hide the attention vector away from the leadership.

If the authoritarian government was presented (an illusion) as a centralized governance that promoted democratization of the free will in the region, then the illusion must be the democratization.

This could be analyzed with an individual's time

Amount of time spent being part of a corporate intent in a lifetime - T years

This also implies the amount of time spent on free will intent - W units

14.4.3 Engineering the sub process

Education system - Spending Y years being taught information and binding the perception to that information - This could be done using the grading system as a reward for compliance - usually in power and reproductive rights

Employment - Constant reinforcement of self-perception for intermediate individuals for being part of a forced intent that was bieng engineered to provide the perception of free will choice

Male - Female - dynamic could be engineered under democracy where males and females have equal rights in performing any actions including leadership. Since democracy was an engineered concept by the authoritarian fifth-dimensional governance, this meant the assigned role for each gender under the flow of creation which has a hierarchy and function had now been disguised to create the perception of free will choice regarding the trajectory for the life pathway.

The free will choice presented for any individual for the purpose of their time was the engineered control mechanisms under their control. The illusion was the separation of any individual and his role in the current territory, his roles, and his responsibility to the law of the land

15 The Perception in human consciousness

Let there be an individual A

Let there be an individual B

The lifetimes of individual A is X years

The lifetime of individual B is Y years

Let there be an interaction of duration D = 5 mins that occurs at some point during their lifetimes.

Suppose Individual A initiates the interaction

Individual B responds to the interaction

Individual A and Individual B both have a perception of their surroundings i.e. the laws of morality for each cluster varies. To illustrate, the laws of morality passed down from genetics include information about interaction mechanics between each group of people.

For example,

The interaction rules between family members

The interaction rules between friends

The interaction rules between enemies

etc

The rules are observed by the individual during the growth cycle and therefore during any interaction between two individuals are based on rules specifically based on the following components :

Purpose of interaction

Morality of interaction - Rate of authenticity of interactions / The declaration of purpose or intent

The integrity of interactions - Accurate self-declaration of morality under different conditions / A cultural code under which a family holds authority in any territory.

15.1 The interaction rules

Since the perceptions of Individual A and Individual B differ according to their parameters, the response mechanisms could vary as follows :

Suppose an interaction starts at t = 0

The initiator presents the subject of the interaction

The attention of the individuals is then fixated on the subject or intent of the interaction.

The perceptions of the individuals in the interaction converge to the subject or intent.

The outcome of this energy from the individuals to the subject creates several trajectories from which the intent could deviate. However, if the attention of the individuals is focused on a specific outcome for the intent then attention energy is diverted into the specific trajectory for the subject or intent in the interaction.

15.2 Intent manipulation

The interactions serve as a medium between individuals for intent manipulation.

Intent manipulation could be visualized as a one-dimensional consciousness virus that fixates the attention of the individual toward components in the memory that induce negative emotions in the individual.

The virus functions by observing the individual's energy levels when the attention of the conscious individual observes various individuals or objects in the surroundings and enters when there is a surge in energy.

15.3 Perception metrics

The perception of the individual at any current moment has the following components with respect to conscious awareness

1. Scale of observation

2. Dimension of observation

The intent manipulation occurs by intercepting the above metrics by locking on to the elements in the target's perception that induce negative emotions in the individuals.

This creates a disturbance in the current moment "t" because the individual consciously observes his surroundings based on free will or intuition however since the perception virus mechanically fixates the attention of the individual with an external force, the free will of the individual is violated.

15.4 The attack of the perception virus

1. Suppose individual A initiates an interaction with individual B with an intent

2. Individual B is infected with a perception virus and does not respond to the intent

3. Individual B reacts to Individual A that is diverted away from the intent thus shifting his attention from the intent to a random element.

4. Individual B continues to react to random elements regardless of individual A's responses

5. The perception virus renders the consciousness of the individual lowered from its current environment so it could direct the consciousness of the individual towards the goal of the virus

6. The goal of the perception virus could be set by its creators. Any individual who has conscious awareness about the laws of creation could consciously create such entities that essentially serve to reduce the frequency of the individual consciousness thus forcing interaction rather than observation.

7. The actions of the individuals in the interaction should be aligned with the intent of the interaction, however, the perception virus alters the actions of the individual away from the intent.

16 The perception of fifth-dimensional entities over Earth Territory

Let a fifth-dimensional plane be drafted from the coordinate system of Earth territory that is defined with Location-Time information.

Let consciousness be defined as the continuous flow of observation. The ability to observe and interact with the surroundings or the self could be defined as one of its properties.

If consciousness could be defined in the dimension over time, the following variables could be used :

Suppose an individual consciousness interacts with N other individual or collective consciousness for a duration of T hours.

The intent of the individual consciousness could be derived by observing its interaction with the other conscious entities.

For example,

If an individual consciousness could be described by estimating its intent in the surroundings, then :

interaction with individual A - duration - x hours - intent (authentic / deception or collaborate / compete)

interaction with individual B - duration - y hours - intent (authentic / deception or collaborate / compete)

.....

During the time of T hours,

All the above data points of intent could be regressed to derive the intent of the individual consciousness.

The Family Tree head count

Suppose an individual who exists on Earth territory is part of a family tree, then the individuals who have passed away or yet to arrive in the family tree could be assumed to be hidden variables.

For any individual at any moment of time t, there are N number of individuals in the family tree that are still interacting with Earth Territory.

16.1 The interaction of fifth-dimensional entities - three-dimensional entities

At any given time t, a fifth-dimensional entity could observe the location of the individual on Earth territory through the co-ordinates (X Y Z t) and interact.

The interaction process of the fifth-dimensional entity

Apply an intent to the individual on Earth Territory through conscious attention on the individual. This generates an external force on the individual. Any individual on Earth Territory instinctively chooses the next coordinate or pathway for movement in each current moment. This process is therefore interrupted when there is an application of an external force on the individual. Let the original pathway instinctively be labeled as x that is chosen at any instant of time for his movement in the surroundings.

The external force then redirects the individual by altering his movement such that there is a new coordinate or pathway where the individual rests which is a new pathway labeled as y.

Therefore, the individual had a target destination of x, however, as a result of the external force, ends in destination y.

16.2 Mechanics of the external force

When the fifth-dimensional entity concentrates on any particular individual on Earth Territory, the intent has an intent for the individual.

Since the fifth-dimensional entity is assumed to be observing the three-dimensional entity on Earth Territory on a location-time plane (X Y Z t), the result of the external force could also be understood by the pathway that is created with the movement.

16.3 Intent of the fifth-dimensional entity

The individual should be the leader of the Earth territory at the time (– x –)

Then the external force that is applied on the individual will alter his trajectory through interactions in his surroundings. The individual will be forced

into interactions that direct the individual's trajectory into the location where he would be considered the leader of Earth territory at the specified time (– x –)

As a consequence, the individuals in the surroundings will also be forced into locations or trajectories to ensure the individual will be located as the leader of Earth Territory at the specified time (– x –).

The principle would be the same independent of intent when an external force is applied to the individual.

16.4 Communication mechanism

The external force could also include communication of intent directly from the fifth-dimensional being to the individual on Earth territory.

The process could also include communication of intent to the individuals in the surroundings, to interact with the target individual to direct the desired intent for the individual.

In practical terms, this could imply redirecting the individual at a particular location and time on Earth Territory.

Since the communication of intent occurs through nonverbal communication, it could be assumed to be private for each individual and cannot be intercepted unless there are beings that are of higher consciousness capacity.

16.5 Hierarchy of power and resistance

The resistance to the external force from the individual could be described as the resistance of free will.

Suppose that multiple fifth-dimensional entities are exerting external forces on any individual, then the resulting target location will be the resultant of the intents of the multiple fifth-dimensional entities.

The impact or the magnitude of the external force that any fifth-dimensional entity could exert on the individual is defined by the following metrics :

Mass of consciousness (The amount of other conscious individuals in his control)

Conscious awareness (The amount of information that could be extracted about

any event or object at any given time) Creative potential (The amount of energy available to alter the surroundings, such as creating trajectories, creating new timelines, new trends, etc.)

The above metrics define a weight from each fifth-dimensional conscious entity and entities with higher weights determine the outcome of the trajectory for the individual.

17 Movement analysis

17.1 The masculine with the largest sphere of influence

Every instant of time for any individual is defined by a radius of a few kilometers that defines their territory of operation. An individual could be described as masculine when he starts accumulating a mass of conscious intents from his surroundings.

The timeline of the masculine/individual could be described based on the number of individuals in his surroundings or in his network, which could be understood as discrete locations where the individuals are operating.

17.2 Relative movement and the information flow field

If the origin of the masculine is understood to be a reference location then the number of feminines who are carrying the intent of the masculine could form the local information field of the masculine.

The location of the individuals could serve as a node that serves as a port through which the intent of the masculine could interact in the local surrounding area of the feminine node.

There, the boundary of the information field is defined by the individual who is farthest away from the dynamic originating of the masculine.

The masculine creates a local information field in the territory along with his global information field that is formed by the external boundary created from the farthest geographic points.

The flow of information is directional and originates from the masculine, then flows through the feminine. At each node from each of the individuals will also create a local information field that is defined by the node's sphere of influence

17.3 The network boundary and quantum entanglement

The sphere of influence for each node or feminine could be restructured based on the masculine-feminine hierarchy that occurs for every conscious intent.

For such a network, any intent created by the masculine will be split by the " n " feminines that are geographically distributed.

Feminines under this context are the individual points that interact within the boundary based on the directional information from the masculine.

Through this network, it is created as a local and global information field that is being controlled by the masculine.

The information field splits the conscious intent of the masculine as a set of conscious intents that are quantum entangled and flow through the appropriate feminine for interaction in the territory

This is because all conscious intent refers to a boundary that has to be defined by a geographic location with respect to the location of the observer.

This quantum entanglement that occurs in the alignment of the masculine intent and the sub-contents of the feminine could be instinctive, particularly nonverbal because the information regarding the individual's movement that is being directed to the attention vector of the individual is being directed by the subconscious information field.

17.4 Creative potential energy

The ability to acquire information from the subconscious information field for the visualization of creating new trajectories is acquired by the creative potential.

The creative potential energy is a function of the ecosystem. Since both the individual and the ecosystem are connected through the information field, this information field alters the movement instincts of the individuals, including groups of individuals as a collective.

The movement data that is observed by the attention vector of the consciousness could also be a function of the relative movement of all the individuals in the territory.

The hierarchy of information that is being directed by the masculine has a network that resembles one masculine, and several feminine structures in the Earth territory.

The relative movement determines the usefulness of each individual (masculine or otherwise) to the ecosystem based on the hierarchical intent set, which then quantum entangles the movement of the feminines in the territory to align with the masculine in the local information field.

The ability to observe the movement of each masculine, and identify the di-

mension in which they observe and interact with, could be acquired naturally through evolution, gain access to the information field through evolution, or enhance the information acquired through technology.

17.5 The mechanism of movement analysis

The intents could be observed through a unique perspective, through varying dimensions of data to understand all the influencing factors that could be observed by data.

The collective observation of intents could be regressed and determine the timeline trajectory based on the global intent of each masculine in the territory.

17.6 Authority and hostile takeover of the movement

The rearrangement of the sub-intents in the information field could to create a newly defined trajectory by the masculine using the principle of least action.

Since individuals who require technology to observe all the dimensions of the objective reality, a duration of time is required for information flow, which could be very large. However, an individual who has a natural ability to access this information could acquire insights by accessing information fields in various territories. Since the process is instantaneous, the rearrangement of the quantum states that occur according to the prime intent of the masculine is instantaneous.

17.7 The geometric masculine-feminine network

The network of the feminines at any given point of time relative to the observer who is the masculine form, as a particular geometric shape.

Then, every set of permutations and combinations of all the possible intersections of those vertices could be defined as various conscious intents that involve the various nodes.

The total number of unique interaction possibilities of all the individuals in the group could be sorted as intents, sub-intents, etc, and so on.

All of those intents could accumulate through the shape of geometry that occurs as a reflection of the alignments of geometric intents.

17.8 The two modes of observation

The observer of each node could either observe the node after defining a boundary on their own, which could either be in a closed system within which the origin is the self, or the origin is defined by some random boundary and placing the boundary outside the boundary

This kind of geometrical analysis of physical matter could be described at the fundamental level as information that describes the order of matter, which is described at that particular time t, where the information that describes the exact photographic replication of the arrangement of atoms or molecules could be stored in the information field of any territory as long as the boundary is defined.

The access to this information is hierarchical, as the flow of creation grows into various new dimensions, which could be represented digitally as the exponential growth of dimensions of data, which could be observed considering their locations are determined.

The number of possible combinations or quantum locations increases exponentially as a function of creative potential in any territory.

The creative potential of any territory is defined by the relative movement of the masculine and feminine arrangements. This process is the information decoding system that could be deduced from the analysis of geometry by observing the geometry in various scales and dimensions at the same time, and equating the movement through various dimensionally reduced forms.

17.9 Illustration

Planetary boundary

An entity could define a boundary over a planetary system and observe the changes at the same time, the observation of movement could be made over the planet Earth as a whole, the boundary where the movement of geography occurs in the day-to-day life, such as employment, education, etc could also be correlated through the continuity principle of movement.

The boundary essentially is the dimensions of the location or the quantum state, and observing it for a duration of T units of time, and then dimensionally reducing it to movement data, such that intent in that location could be understood as relative movement data.

The movement data could then be captured from all the equipment that is capturing the movement in the solar system, from the planetary scale to local neighborhood traffic movement.

17.9.1 The proximity of extra-terrestrial observers

They have to be attached to planetary bodies to be around the trajectory of the Earth. The hidden stable trajectories around Earth and the nearest bodies surrounding Earth, such as the moon, Venus, etc, could be used for tactical advantage, especially if they have camouflage technology to observe the larger boundaries of Earth's territory.

Once the movement data is captured, it could be replicated with digitization such that automation of the movement could occur, which could be engineered and serve a purpose specifically capturing the dimensional coordinates of origin.

The Earth as the origin has a signature for its movement, which could be observed and digitized for any species as an intent. In such a scenario, the intent structure that is stored in the Earth's territory could respond with movement to serve as an immune system for Earth's territory

18 Defining random fate in the dimension of Time

Let an individual be born at time t = 0

Let the individual die at a time t = T years

An individual's lifetime of T years could be defined by the technique of dimensional reduction. The lifetime of the individual could be reduced to the number of individuals he or she interacts with.

Suppose the individual meets N other individuals, which could be generalised as the following subgroups. The time that an individual spends with either friends or family is assumed to be mandated, and the category other implies that the interaction could be voided.

Family (includes parents, wife, kids) - X hours per day dedicated to interactions between family members

Friends - Y hours per day dedicated to recreational interactions

Others - Z hours per day dedicated to work interactions, random short-term interactions etc

...

Therefore, the above time spread could be described by adding another variable such as :

X hours spent with " n " individuals per day

Y hours spent with " m " individuals per day

Z hours spent with " p " individuals per day

18.1 Defining an individual through interactions

An individual therefore spends the average 24-hour day cycle on Earth Territory spent between Sum = (n + m + p) individuals.

For the individual, the relationship between the total Sum of individuals he interacts with per day could be described with time.If the total time spent by the individual could be sorted in each group by the descending order of duration

of time spent with them :

Family - Total time spent - X hours

The top three individuals who shared the most time within the family subgroup

Individual A

Individual B

Individual C

Friends - Total time spent - Y hours

The top three individuals who shared the most time within the friends subgroup

Individual X

Individual Y

Individual Z

Other - Total time spent - Z hours

The entire set of individuals who shared the most time within the other subgroup

Individual a

Individual b

Individual c

.....

Individual N

18.2 Fate and interaction with individuals

Suppose outside of the friends and family subgroup, a fated event were to occur, then it could be assumed to start with an interaction with any one of the N individuals for the sample Individual.

The process of the fated event

Suppose an individual interacts with N individuals under the other subgroup during his 24-hour day cycle on the Earth Territory, then

The duration of interaction time between the sample individual and the other N individuals starts increasing until they are reclassified as friends or family.

The fated event could either be engineered by other individuals or could occur randomly.

To illustrate,

A family set up between two individuals could lead to marriage, and their interactions are reclassified as mandatory.

On the negative side, certain interactions could be engineered to look like fate, especially in the context of forced manipulation of free will. Such as the introduction of a romantic relationship to acquire secrets, implanting friendships that could be aligned to resemble " Fate " or consciousness deception. The idea being that the external stimuli could be engineered to produce very specific instincts in the average individual.

18.3 The method of situation engineering using external stimuli

Suppose an individual on Earth territory could be observed from a fifth-dimensional plane of existence, then his movement over time could be traced throughout his lifetime using the coordinates (X Y Z t) where X, Y, Z, t are relative to the observer.

The individual could be isolated to exert external force from the 5D plane, which then produces a response from the individual. The response of the individual could be measured by the change in movement that occurs after the application of the external force.

An individual is located on Earth Territory through coordinates (X Y Z t)

An external force is applied to the individual from the 5D plane

The change in coordinates that occur is observed and the response is recorded geometrically.

The external force is repeatedly applied and the consequent responses are ob-

served.

The responses from the individual are collectively stored and a situation could be regressed on the individual's movement based on various scenarios.

If the individual's reaction could be regressed by a single external force, then computational power could be used to regress a sequence of external stimuli over a time period to alter the trajectory of the individual towards a target destination.

The application of the external forces could be achieved by strategically placing individuals surrounding the target individual, who interact when necessary to plant the necessary external stimuli.

Therefore, the strategy of situation engineering is therefore location-time based tracking on a defined territory. If any territory is defined by a boundary, and several individuals are placed in the defined boundary, where each individual has a defined sub-territory.

The protocol would then be to trace the individual, identify plants in the surrounding sub-territories, and divert their attention to the target individual with an intent.

The intent in this case, which is targeted towards the "Target individual," is concious attention energy that is intended to force an outcome.

This external force, which is applied to the individual from his surroundings, to force movement in a particular manner forms an integral part of situation engineering that could be designed in any territory.

18.4 Defining family through the marriage of the Time contract

The process of marriage binds two different families by a contract of law.

The law is defined by the collective perception of the local surroundings.

Because of the ritual of marriage, it was always intended for the permanent merger of families, producing a new strain of genetic material by reproduction.

This process requires energy transfer from one family to another, meaning that the family with the lower creative potential could drain the other until the creative potential averages out.

The process of marriage is a hidden communication link between the families that results in energy transfer as and when needed.

Since two nodes or families are linked together, the energy balances out in terms of wealth, attention transfer or energy transfer by causing energy distress.

19 The timeline prediction algorithm for the attention vector of an individual

Let there be an individual A located at a location " x "

Let there be " N " individuals in the surroundings for individual A such that they are the individuals who interact with individual A with the highest probability at any given time " t ".

The interaction could be further discretized as spending an amount of time "dt" with one or more of the individuals based on the specific intent at a time " t ".

The intent could be broadly classified as the following :

survival needs (hunger, livelihood, etc.)

non survival needs (companionship , hobbies etc.)

reproductive needs (all activities concerning sexual instinct)

19.1 The movement and the attention vector

Suppose if the individual has an intent at time " t " that cannot be fulfilled at location " x ". Let the intent be assumed to take an amount of time " dt " units.

Suppose if the individual has an intent at a time " t " that cannot be fulfilled at location " x ", then he has to relocate to location " y ".

The location " y " could be a variable such that it could depend on the attention vector specifically the choice of one or more individuals for the interaction of duration " dt " units of time.

Once the choice of companion for the intent is made, the attention vector of the individual directs the individual's movement from location " x " to location " y " like a consciousness GPS system.

There could be " k " pathways to get from location " x " to " y " and the attention vector of the individual navigates the best possible trajectory.

19.2 Engineering the choice of individual

If individual A has a choice for the intent that could be individual B or individual C, then the attention vector also directs individual A towards the location of the individual that is based on the best fit for forward movement.

However, if individual C had an intent to be a part of the intent of the individual A , then he could engineer the attention vector by applying one or more several external forces such that more attention is diverted towards individual C to maximize the outcome.

The awareness of individual C towards the intent of individual A at a time " t " could also be engineered through observation of the individual at a time " t ". This could be any kind of surveillance that could be technological or otherwise such as an observer in the vicinity of individual A that could exchange information with information C.

The information exchange between the individuals could occur with or without their awareness.

19.3 Reverse engineering the timeline

Let the individual A be the target for reverse engineering

Let one of the " n " individuals have an intent such that the timeline of individual A could be engineering for a duration of T units

19.4 The Engineered trajectory for a duration of T units

Let the duration of time T units be split as T = dt1 + dt2 and the intent to engineer the trajectory is as follows :

At t = 0,

Shift Location " x " to Location " y "

stay in the location " y " for a duration of " dt1 " which is the duration of interaction at Location " y "

At t = dt1,

Shift Location " y " to Location " z "

stay in the location " z " for a duration of " dt2 " which is duration of interaction at Location " z "

The above situation could be engineered at various locations by applying external forces at any of these locations " x ", " y " or " z ".

The external forces take the form of any individual or an object such as an electronic device that is capable of diverting the attention vector of individual A.

19.4.1 Illustration

Suppose if individual A had a trajectory with the variables { dt1 dt2 x y z } defined by the attention vector, then

The choices for all the variables above could be different for individual A and individual C, but individual C could introduce another interaction of duration "dt3" units at any location (virtual or physical) such that the attention vector of individual C diverts one or more of the variables in the trajectory of individual A as a result of the additional force applied in the interaction of duration " dt3 " units.

19.5 The probability spectrum of choices

Let an individual has been observed for a period of time either through the perception of the surrounding individuals or through information surveillance that could occur in any shape or form.

The purpose of the information is specifically about the unique relationship between an individual's attention vector and the movement preferences of the individual.

The attention vector of the individual could be correlated to the individual's movement choices specifically if there are multiple trajectory possibilities to get from A to B, then the individual is most likely to choose the best trajectory possibility.

The principle could be extended to individuals, locations, etc because the individual is always likely to prefer the forward pathway according to his " m " territory or " n " family tree intents that are directing his movement trajectory like a consciousness GPS system.

20 The Timeline Intersection Strategy

Suppose that there are " N " individuals in the territory.

Let there be " M " masculines in the territory.

Masculines could be defined as individuals whose conscious awareness is higher than the average individual and thus have access to a larger amount of information or data to allow for greater control over their surroundings (which may or may not include other individuals).

20.1 Simplified Timeline representation of an Individual described by the following information (or time series)

Past (t = -dt) , the individual moved from location " x " to location " y " after spending an amount of time "dt" in location " x ".

Now (t = 0), the individual will move from location " y " to location " z " after spending an amount of time "dt" in location " y ".

Future (t = dt), the individual will move from location " z " to an unknown location but the location " z " is still an unknown state because the analysis is always done in the " now " at t = 0

20.2 The variables in the timeline

Since the current timeline could be discretized with various locations, the assumption is that each moment is not defined by time but by the amount of time that the individual spends in each location.

For the simplicity of the analysis, we are assuming the individual spends an equal amount of time (dt) in each location , however, the variable " dt " is likely to vary as the individual goes from one location to the other but the analysis format is unlikely to change.

20.3 The conscious intent in each location

The following three activities could be assumed on a consciousness level

Observe

Interact

Experience

The following three activities could be assumed on a biological level

Survival needs

Non-survival needs

20.4 The Attention vector or the life force of movement from one location to the other

The attention vector of the individual drives his activities from one location to the other which could be defined as the following two metrics of continuity that describe his purpose or intent.

Territory Tree intents " m " - The assumption for these intents are based on balancing the ecosystem such that several intents could be hardwired into the creation process for various applications which may or not be known because consciousness could be created with a few deterministic instincts based on balancing various other instincts in the ecosystem.

Family tree intents " n " - The assumption for these is that any family tree that has survived until the current moment has done so based on specific instincts that are tailored for the ecosystem that is defined uniquely based on each masculine of the family tree. These instincts could include family-based skill sets, crafts, and interaction keys (how they choose to interact with various other species including the ecosystem with traits such as deception, collaborating tactics, and competing tactics, etc.

20.5 The average interaction

In any average interaction that is assumed to last for a duration of " dt ", there could be one or a group of individuals such that their attention life force is assumed to be attached to one or more objects or individuals in the interaction. This could be visualized as a metric that is holding the attention vector of the individual in that interaction if not there could be no reason for the individual to be in that interaction.

It should also be noted that the experience of the interaction is independent of the attention vector, the bind is simply a function of the life force or attention of the individual in the interaction.

For simplicity, the interaction of any individual could be represented as the following :

Primary attention metrics

Secondary attention metrics

While the above could be subjective based on the individual's independent " m " and " n " intents, it could be understood as a string of energy from the individual that has attached to various objects or individuals in each location interaction such that it could be a relevant piece of information or metric for his life-force for forward movement.

If an individual has two energy strings as a primary metric and two others as a secondary metric then it could be assumed to be a continuity factor (or a dependent variable) that will allow his attention vector to choose his next location " z ".

20.6 The Probability of the future trajectory from the current movement

If individual A is assumed to be at the current moment at t = 0, the location is assumed to be at " y". The forward movement could that occurs after " dt " units of time could be described as hypothetical states that is described by the primary and the secondary attention metrics in each interaction location.

For simplicity, the location " z " could be assumed to be three possible locations z1 or z2 or z3 based on the exchange of information that occurs in each location.

For any observer, each location becomes a probability based on the metrics or information of movement that he is observing.

20.7 The trajectory plotting from the current location to the target location

The interaction that occurs in the duration of "dt" units directs the attention vector of the individual after "dt" units of time depending on the priorities defined by the primary and secondary attention metrics during the interaction at location " y ".

Since the choice for " z " could be any of the following possibilities set by the attention vector of the individual :

Stochastic

deterministic

At t = dt, if the individual could choose his trajectory to either z1 or z2 or z3 then there are three probable states for the timeline of the individual for his next location.

20.8 The time of the decision

The probable states are a function of the primary and secondary attention metrics however the exact location and time where the trajectory could be set for t = dt could be variable as well.

20.8.1 Nonlinearity of time

For instance, if the linearity of time could be ignored then the decision to choose the Location " z " at t = dt could either occur at several time steps before or after t = dt.

Where the implication is that the choice to choose the exact location at t = dt could either have occurred several time steps in the past or several time steps in the future.

20.8.2 Masculinity and control of information flow in the time dimension

Suppose that the masculines in the territory could make such decisions because of their higher conscious awareness that could include the time dimension. The possibility arises because of the fact that increasing awareness of the surroundings will provide greater control of the surroundings including altering instinct in the past or the future through quantum entanglement of consciousness through its specific " m " and " n " intents.

20.9 Interaction of two masculine timelines

Suppose if the target destination for individual A could be at Location " z = z1 " from location " y " at the current moment which is now.

There could be another individual B in the interaction at location " y " such that he could apply an external force at t = 0 such that the trajectory of the individual could be diverted to the locations " z2 " or " z3 ".

20.9.1 Engineering the process

An Individual B could introduce an Event or an individual into the primary or the secondary attention metric of Individual A such that the perception function of Individual A will be forced to consider the additional pieces of information concerning the event or the individual in his attention vector to plot his trajectory.

The manifestation of the applied external force by individual B could alter

the probability of his movement to go to " z1 " depending on the force applied which in a literal sense could divert or obstruct his trajectory to "z2" or" z3".

The trajectory of individual A could have momentum for his trajectory driven by his " m " and " n " intents as it traverses from one discrete location to another after spending "dt" amount of time in each location.

20.9.2 The impact of the external force

The external force that is introduced into the interaction in the current moment could either serve as an alignment force or an opposing force to the trajectory of the individual A which is estimated to be z = z1.

Since an individual has an intent for every event or individual that is in his primary or secondary attention metric in any interaction (at any location), it could be assumed that each conscious intent could serve as a movement vector force in the local subconscious information field with a magnitude and direction that is driving the instinct for movement from the current location to the target destination.

20.10 Contradictory projection of intents

Suppose if the external force that is applied by individual B creates choke points in a linear sequence during the interaction that serves as attention triggers for movement resistance such that the overall intent that is driving the movement from one location to the next could be slowed or altered completely, then the principle of deception could be applied in the following manner.

20.10.1 The deception mechanics

The event or the individual that is introduced as an external force by individual B to the attention vector of individual A could have a projected intent such that individual A assumes the purpose of the external force is an alignment vector force rather than a conflicting vector force.

In such a case, the conscious intent vectors that are driving the forward movement from " x " to " z " will have two perceptions of the movement that could occur.

Therefore two contradictory perceptions will drive the forward movement as a result of individual A having his attention on an event or individual that is covertly plotting an alternate trajectory for individual A.

This method of deception includes the association of the external force in his

timeline for the conscious decision-making from one location to another. This could then in theory re-adjust the probabilities for z1 or z2 or z3 depending on the conscious awareness of individual A regarding his interactions.

20.10.2 Decoupling the deception using conscious awareness

On the other, if the exact description of the external force could be identified by the individual by decoupling the true intent of the event or the individual. This could be identified by identifying the information or data that is driving the deception.

The association of the information to the deceptive movement would allow the force to be commanded by identification (or name).

A relative movement that is occurring with a purpose under the deceptive projection could be identified by name with conscious awareness.

The identification of purpose via discernment will establish masculinity in the local subconscious information field which will allow to redirect the force vectors affecting the location trajectories in the local subconscious information field to align with the global subconscious information field which is more aligned with masculine through his conscious awareness.

The ability to align and control the force vectors in the sub-masculine or non-masculine's local subconscious information field occurs through the interface commonly called as the event horizon between space-time and the global subconscious information field that drives the instinctive movement of all conscious intents in the defined boundary of space-time.

The access to exchange information through the interface occurs through the authority defined by the hierarchy of conscious creation in the territory.

20.10.3 The force vector redirection

In this case, the redistribution of the probabilities for the target destinations of all the individuals could occur such that both conscious intents will contribute to maximizing the destination " z1 " defined by the masculine.

This could be accomplished by commanding the vector to act on the various points of contact connected through the attention vectors of all individuals connected with intersecting information in the specific interaction location. In a literal sense, all the information that is connected to the interaction through

the energetic trail of attention from all the individuals.

The magnitude of the force from each conscious intent could be directly proportional to the potential and kinetic energy of the life force driving the individual through his "m " and " n " conscious intents.

The magnitude of the external force applied by individual B as an opposing force to obstruct the movement of individual A could be redirected to affect any of the points of application which is connected through the invisible energy trail of attention.

In a literal sense, the interaction that occurs at any location with several individuals could trigger all the locations from the local subconsciousness information fields to be projected into the global subconscious information field as possible trajectories.

This process could help identify all the contradictory trajectories in the global subconscious information rather than the local ones.

In such a case, the external force could be redirected to any location identified in the global subconscious information field with an intent such that the force vector could boost the intent of the masculine by altering the circumstances of the non-masculines to boost the trajectory of the masculine.

21 The consciousness management system

Suppose an individual's consciousness could be described as a location reference similar to a GPS system where the attention vector of the individual directs the movement of the individual.

Suppose the attention vector of the individual is naturally aligned to the " m " territorial intents and " n " family tree intents.

The mechanism of the location reference and the intent could be engineered in the following manner.

21.1 The movement

Suppose if individual A has " N " individuals in the conscious awareness of his attention vector (consciousness) at any given time t = 0 (current movement),

If the location of individual A is assumed to be the origin which in this case is assumed to be " y ", the forward trajectory of individual A could be assumed to be correlated with the current and target locations of the other individuals.

21.2 Simplifying conscious awareness to locations

The conscious awareness of the individual could then be described as all the locations (assuming X = number of locations) that the individual could access from the global subconscious information field that is quantum entangled to the local subconscious information field through the attention vector of the individuals in the location interaction.

The locations could then be sorted based on the probability of reaching that destination from the origin (individual A) in the next discreet time step t = dt.

The location of the " N " individuals which could be located in any one or more of the locations could be harvested for all their current and possible target trajectories to engineer a new trajectory for individual A.

21.3 Optimal trajectories for individual A

The distance between the current location " y " of individual A to the set of possible target destinations " z " could be described geographically.

Suppose if there are multiple trajectories possible for " z " there is another random number " K " which describes the number of ways an individual could go from " x " to " z " .

Since there could be several possibilities for " z " , then the total number of pathways to go from " x " to " z " could be K*z

21.4 Illustration

Suppose individual A and individual B are in an interaction location of duration "dt" and the trajectory of individual A is to be determined.

Suppose there could be two destinations that are most probable for " z " such as:

" z1 " - Favored by individual A's timeline

other - Favored by individual B's timeline

21.4.1 Applying the law of minimal action to estimate optimal pathways

The trajectory probabilities are determined by the attention vector of the consciousness based on time and energy which is deduced from the distance estimate based on the current relative locations of individual A and the " N " individuals available in the global subconscious information flow field.

The optimal path to traverse from " y " to each one of the possible destinations in the subset z = { z1,z2...} could be the shortest path to get from one location to another.

21.4.2 Illustration

" x " to " z1 " - Estimated distance d1

.....

" x " to " zn " - Estimated distance dn

The subset d = { d1,d2...} contains only the shortest or the optimal path to go from " x " to various possibilities in set " z ".

The assumption here is that the shortest distance implies that the least amount of time and energy is needed to travel to each of the possible trajectories in z = z1,z2,... through the optimal pathways selected with the set " d ".

21.5 The Perception function

The above process could be intuitively estimated by the perception function of the individual consciousness who is traversing from the current location " x " to the target location " z " as part of the natural translation process that occurs

from the geometric language of relative movement to the movement language in space-time.

21.6 Estimating the quantum state of locations

Suppose the individual consciousness has a set of intents at time t = 0 such as I = { m1,m2...n1,n2 } then the exact trajectory that is chosen for the target location " z " will be based on the distance optimization based on the Intent set " I " which could be assumed to be a superposed state of the individual at a time " t ".

21.6.1 The Perception function P(t)

The superposed state could be defined by the perception function P(t) of the individual which uses the various boundary conditions to correlate the information in the surroundings to the relative movement of the " n " individuals in the surroundings.

The boundary conditions allow to observe the relative location of all " n " individuals relative to the observer location which in this case could be assumed to be location " y " at time t = 0 which is assumed to be the origin.

21.6.2 Defining the Boundary conditions

The boundary conditions could be assumed to be a kind of targeted GPS system where each boundary condition has a set of information (" d " dimensions of information) such that if it is used by the perception function P(t) to observe the relative movement in the surroundings, it automatically correlates the movement to the " d " dimensions of information stored in each boundary condition which then concludes an intent for the relative moment.

21.6.3 Estimation of intent

If there are " k " such boundary conditions that describe " k " intents as a possible explanation for the relative movement then the superposed perception function P(t) could estimate the most probable intent for the relative movement observed.

The higher the accuracy of the boundary conditions of the perception function to associate relative movement to various pieces of information the more accurately the individual could observe and interact with the surroundings because it provides greater control over the relative movement in the surroundings. This could be done by diverting, distracting, or removing pieces of information that are driving the movement in the surroundings.

21.6.4 Exact Solution to the intent deduction

The exact information that is driving the movement could in theory be deduced by the rotational observation of all the superposed perception functions associated with any defined boundary.

Rotational observation could be defined as the ability to observe the superposed perception function P(t) of all conscious intents that provide energy to the relative movement in any surroundings through their attention.

The observer equation describes the amount of energy (attention) that defines the event horizon or the boundary of observation.

The more accurately an individual could observe the relative moment of " N " individuals and deduce intent in the surroundings, the more predictable the movement of the " n " individuals become for their future trajectories.

21.6.5 Forecasting movement

In terms of stochastic estimation, there could be " Y ={ y1,y2...} " possible pathways that each individual could take for their forward movement.

The total number of trajectories that could be foretasted by the individual observering consciousness could be defined as N * Y.

Where it assumed that there could be " N " individuals in the boundary being observed.

Where Y is all the probable destinations that each individual could based on his attention vector.

21.6.6 The observer within the boundary of observation

Suppose if there is an individual A that has plotted a movement trajectory to go from location " y " to location " z1 " after a duration of " dt " in location " y ", then the forecasting N*Y trajectories for all the individuals in the surroundings could allow creating the optimal trajectory that will not interfere with the other trajectories to avoid any kind of forward movement.

21.7 Quantum States of locations defined by movement

Suppose that the observer could describe the possible trajectories of N individuals in any location " z " as various quantum states possible for the location " z ".

The observer is plotting his trajectory for the forward movement based on the

navigation or intersection of these various quantum states in the location " z ".

Let the total number of trajectories to be forecasted for each individual in the surroundings or boundary be defined as Q = {q1,q2,....}.

21.8 Each possible trajectory for an individual

Each trajectory "q1" could be split across by the following discretization of the trajectory

Assuming that all the trajectories could be observed simultaneously regardless of the individual who could take the trajectory then,

21.8.1 The trajectory q

t = 0

location 1

t = dt

location 2

....

21.8.2 The interpretation of the trajectory

The observer individual A who could in theory observe all the trajectories as quantum states for the location " z " defined over the boundary which could N*q.

Where N is the number of individuals in the boundary

The number of possible trajectories for each individuals is defined by the set " q "

21.8.3 The trajectory of the Observer by quantum jumping

The observer could then take any random trajectory to traverse from the location " y " to the location " z ".

21.8.4 The trajectory of the Observer

At t = 0 ,

take q1's choice of trajectory to go from location " 1 " to location " 2 ".

At t = dt ,

take q4's choice of trajectory for location 8

etc.

21.8.5 The interpretation

In theory all of the trajectories that are possible could be split based on various time intervals defined by "dt", and the locations of each individual at each checkpoint could be defined as Location 1, Location 2, etc.

Each of these trajectories could have different locations at each checkpoint where location 1 of trajectory 1 in the trajectories set (N*q) could be different from location 1 of trajectory 2.

This could be possible even if trajectory 1 and trajectory 2 are possible trajectories of the same individual.

Under this context the total number of possibilities for the movement of individual A for his movement trajectories is a large set of locations.

Suppose that each trajectory is discretized into "K" discrete time checkpoints in the overall trajectory set defined by N*q then the number of locations that the observer could quantum leap is defined by the equation K*N*q

Suppose if individual A had a fixed trajectory to go from location " x " at time t = 0 to the location " z = z1 ", the observation of the exact trajectory to take from set of K*N*q could be proportional to the quantum state of the location to be reached at the location " z " where z1 defines the relative movement in the location " z " that defines its quantum state.

22 Time and state-based mechanics

Let the individual A be located at the location " X " at current time " t "

Current State

Let the current state of the location " X " be defined as " A "

The individual A is in a known psycho-energetic state where the individual has a limited amount of :

the kinetic energy K as an accumulated intent flow from his last current state to the current state at time " t "

The potential energy stored in individual A such that it could be used for the navigation of the current trajectory towards his next trajectory " Y "

This state carries a natural trajectory toward an outcome based on his intent that is keeping him in motion.

Let the next destination of individual A be defined as " Y "

Target State

Let the natural desired state be defined by the movement of the natural trajectory upon entering " Y ".

The state in this context could be defined through the intent of the individual specifically if the individual has an objective then the circumstances at the location " Y " must allow him to establish his intent through the circumstances.

22.0.1 Illustration

Suppose if there are " n " circumstance states in location " Y " and half of those states allow for the objective of individual A and the other half don't.

This could visualized as using a restaurant as an example.

Suppose two waitresses are working in the location " Y " which is a restaurant.

If individual A visits location " Y " every day at the same time then he gets a free cake from one of the waitresses and nothing with the other.

Therefore individual A starts to alter the time that he enters the restaurant by a few minutes here and there such that he gets placed at a table being served by the waitress who offers him the free cake.

Therefore the timing that is defined by observation that he makes from the location " X " before entering the location " Y " defines the probability of the state with the free cake.

Individual A needs to invest energy (time, attention, emotion) through a set of actions (set of tasks, preparations, or interactions, etc) such the right kind of observation occurs for the navigation of the states.

22.1 The energy state of individual A

The current state of individual "A" at location " X " could be defined further by the number of individuals in the locations.

Let individual A be surrounded by two other individuals :

Individual B

Individual C

The energy distribution could be described as follows :

Individual A has an objective " O " for location " Y " for which he must perform " x " actions such that it requires " T " units of time and " E " units of energy (kinetic, potential, and attention)

22.2 The Energy influence of the surrounding individuals

Let individuals B and C have an objective " O_ bar " for location " Y " such that it is contradictory to the objective " O " of the individual. Therefore individuals B and C must perform " x_bar " actions such that they require " T_bar " units of time and " E_bar " units of energy (kinetic, potential, and attention)

Suppose individual A has a finite amount of energy " E_total ", time " T_total" then the proportion of time and energy that goes to " x" or " x_bar" decides the target state of the location " Y " because the state is a reflected through the observation and interaction effort to reach that state.

The actions then consequently decide the target state" Y " which is either

" O " or " O_bar "

Individuals B and C emit emotional energy, attention by observation, and intention, which acts as a field that intersects with A's field.

If B and C consciously or unconsciously focus energy on alternate possibilities for location Y with O_bar, they open energetic channels toward alternate timelines which increases the probability weight of diverging states.

Furthermore, the probability of the diverging states for individual A could be increased by creating another interaction with B and C with " E_ext " amount of energy and " T_ext " amount of time such that time and energy from individual A could be forced into the " x_bar " actions.

Mechanics of Attention Diversion B and C could introduce unnecessary variables, topics, urgencies, moods, or emotional pressures from Set Y (unrelated trajectories) that go from location "X" to location " Y".

These act as attention traps: emotional conflicts, distractions, irrelevant obligations, mood manipulation, and altered priorities.

A is now leaking energy into a non-resonant field thus misaligning his energetic frequency with his intended trajectory.

The leaking energy causes internal alignment shifts (he starts investing belief/emotion into a different path) from his intended trajectory with " x " actions which redirects his physical time and energy.

His resonance with the expected state " B " for Location Y weakens, while alternate outcomes gain energy mass.

22.3 Engineered Outcome

This process can be covertly engineered by:

Emotional mood seeding (making A anxious, angry, nostalgic).

Inserting false urgencies (tasks that seem important but are misaligned).

Manipulating presence (deliberately showing up or withholding support).

Altering group dynamics (group expectations, alliances, and narratives).

This shifts the collective field, weakening the frequency signal of A's intended

trajectory, thus increasing the chances of collapse, delay, or complete redirection.

The present moment is always vulnerable to energetic interference, especially from others entangled in your field. If these others focus intention or manipulation toward alternate outcomes, they don't need to physically block your path — they only need to redirect the attention of the target individual.

In modern terms, this is like subconscious timeline hacking or rerouting destiny by draining the fuel (TIME and energy) away from the intended path.

23 The Energy distribution mechanism through movement

Suppose if there are " n " individuals located in a location " x " at time " t "

Let there be a movement that is occurring in the location " x " which is defined as the movement that is occurring from each of the " n " individuals where each individual is assumed to be at a different sub-location " x1 ", "x2", " x3 ".... at a time " t ".

23.1 The relationship between location states and movement

The current state of the location " x " could be defined at time " t " as " A " which consequently defines the exact sublocation of each of the " n " individuals .

The target state of the location " x " which could be defined at a time " T " as " B " which will be the expected sub-location " y1 " , "y2 , " y3 " ... at time " T "

Let each one of the individuals have an energy field that is driving the movement vector field such that potential and kinetic energy (E) that is acting on the movement vector field is directing the movement from " x1 to y1 ", ..." xn to yn " etc.

23.2 Interaction of the energy field and the consequent change in the movement vector field

Suppose if each individual's movement between state A to state B could be defined as a timeline between the time periods of time going from t to T.

Consider the movement of individual " one ",

time t

location = "x1 "

individual " one " interacts with individual " two " , " three , "and seven " therefore the energy fields of the individuals (E1, E3 , E 7) are interacting with each other such that depending on the magnitude of the stored potential energy (P1, P3, P7) and the kinetic energy (K1, K3, K7) of each individual

which could vary.

23.3 The origin of the direction force in movement

As a result of the variation in energy fields, energy from the individual with the higher energy field flows to the individual with the lower energy field, and as a result of this increase in entropy, a force is generated from the lower energy field that absorbs the energy which then acts on the higher energy field which then acts on its movement vector field.

Therefore a directional force could act on the movement vector fields of each individual during the interaction. Suppose if there are four individuals interacting then all the possibilities are illustrated below.

From individual one,

a force " F12 " acts from the energy field of individual " one " to the individual " two"

a force " F13" acts from the energy field of individual " one " to the individual " three"

a force " F17" acts from the energy field of individual " one " to the individual " seven "

From individual two,

a force " F21 " acts from the energy field of individual " two " to the individual " one"

a force " F23" acts from the energy field of individual " two " to the individual " three"

a force " F27" acts from the energy field of individual " two " to the individual " seven "

.....

Therefore could be F12, F13, F17 , F21, F23, F27 , F31, F32, F37 , F71, F72, F73 direction forces that are acting in the location " x1 ".

23.4 Creation of direction force using potential energy

While the natural dissolution of energy could only imply one force (F12 or F21) could act between two individuals such as between individuals one and two, both directional forces could exist in the interaction.

This is because directional forces could in theory be created from the individual with the lower energy field to the individual with the higher energy field by movement consent. For example, the individual with the lower energy field could reduce its energy further by providing its energy to the individual with the higher energy field against the natural dissolution of energy.

The natural dissolution of energy implies going from order to disorder which is the flow of entropy. However, reversing the process implies recreating order such that the energy flows from the lower energy field to the higher energy field.

This process could be engineered such that another fragment of energy is used from the individual with the lower energy field such that its movement vector could altered such that energy flows to the individual with the higher energy field.

This process could be established by directing the attention vector of each individual in the interaction such that the movement that is occurring as a natural state of energy dissolution to achieve equilibrium could be altered to another state where it creates an unnatural state of energy dissolution such the overall state in the location " x1 " is further pushed away from equilibrium which increases the probability of energy depletion.

This is because with every incremental increase of energy that is needed to maintain the flow of energy from the lower energy field to the higher energy field is drained from the potential energy of the individual with lower energy. This reduces the total amount of free energy from an individual at a faster rate if they are providing energy to the individual with the higher energy.

23.5 Natural dissolution of energy through movement

Suppose if there are four individuals in the interaction in the sub-location " x1 " then if individual one has the highest amount of energy, then if the above process of energy extraction is implemented in the location the change in state could be represented as below :

The current state of the location " x " with four individuals interacting at " t " which is A

location of individual one ” x1”

location of individual one ” x2”

location of individual one ” x3”

location of individual one ” x4”

The expected target state of the location ” x ” with four individuals interacting at ” T ” which is B

location of individual one ” y1”

location of individual one ” y2”

location of individual one ” y3”

location of individual one ” y4”

23.6 Engineering the state change to maximize energy drain

However, if the above process is engineered such that the dissipation of energy occurs from the individuals with the lower energy fields to the individual with the highest energy then the forces could be represented as below :

The engineered target state of the location ” x ” with four individuals interacting at ” T ” which is C

Under the natural conditions of energy flow the change of location of each individual should have occurred from ” x1,x2.. ” to ” y1,y2... ”

However, an additional force that acts on each individual will alter the movement vector of each individual such that the locations at the target state will change for the individuals to ” z1,z2... ”.

location of individual one ” z1”

location of individual one ” z2”

location of individual one ” z3”

location of individual one ” z4”

The distance between the intended location " State B " and the target location " State C " (from " y " to " z ") could be described in terms of the amount of energy that is needed to engineer the movement could be described as potential energy that is drained from each individual for the addition work of the movement.

Any employment location could, in theory, be represented as the sub-location " x1 " where " n " individuals are in a movement that could be simplified as the change of state from " A " to " B " and then to " C ".

This process could be engineered such that if individual one has the highest amount of energy then by embedding the location " x1" with various movement patterns such that there is always an additional movement that results in a change in state from " B " to " C " for each individual such that there is always energy transfer to the individual one who has the maximum amount of energy.

23.7 The employment energy system

This process could in theory be enforced through various mandated movement procedures such as trajectory tracing and reporting to individual one in the sub-location " x1".

For any individual in an ecosystem, an amount of energy is needed such that his survival needs can be met. The energy is used for movement such that a change of state occurs after his survival needs are met from " state A - survival needs not met " to " state B - survival needs to be met"

The above process of " life movement " could be engineered such that by establishing nested sub-locations where the " life movement " of individuals could be engineered to include the " State C " . The engineering process could be established with various methods such as :

Restricting survival needs resources until compliance to force " State C "

Deception of intent in the interaction to include " State C "

The above process could be further enforced if the conscious awareness of individuals could be reduced as much as possible through perception engineering such that compliance and survival vulnerability is maximized.

24 Movement Mechanics and the Ecosystem

24.1 The balance of intents in the ecosystem

Each conscious intent is specifically correlated to " n " dimensions of information in the ecosystem.

The intent is movement information for the " N " individuals in the Ecosystem such that a change of state occurs from the current state to the target state.

Each individual that was specifically born at a location " x " has " m territory intents " and " n family tree intents " that define his impact in the ecosystem

Where each of the intents could be described as a set of instructions that describe intents for each of the N individual's time.

Therefore the impact of any individual could have the following structure :

The change in movement information that occurs for each of the N individuals surrounding the individual according to each intent

Collectively if an individual has " k " unique intents then the superposed movement information that occurs for the surrounding individuals could have an impact on the overall geometry of the ecosystem,

If an individual is introduced at a location " x " at the current state then as a result of his " m " conscious territory tree intents and the " n " family tree intents the change of geometry occurs from the current state to the target state.

Suppose if the current state of the location " x " is defined by the geometric structure of the ecosystem .

Let the geometric state if the current state be defined as A. An individual is introduced at the location " x " with " m territory intents " and " n family tree intents " at current time " t "

Let the target state where all the " m + n " conscious intents have been established be called B.

Therefore the purpose of the " m and n " intents have been accomplished and the individual's purpose for the location has been established.

The intents could also have other metrics such as :

24.2 The rate of change of geometric state from A to B

The impact of the geometric change on the ecosystem and vice versa. In theory, the ecosystem itself could have its own " m territory tree intents " and " n family tree intents ".

This implies that any ecosystem could be collectively represented as one entity (with N individuals in movement) going from current state A to target state B.

If the " N " individuals themselves are interacting such that each individual is a fragmented part of the ecosystem's " M " and " N " intents.

Suppose if any ecosystem comes from a void, then the purpose of the individual ecosystem could have been created such that the change of state from current state A (which could be void or otherwise) to the target state (An altered state of the ecosystem)

Suppose the ecosystem could have several intents such that each individual's movement that is occurring is based on his instinctual movement in the ecosystem that is being directed through the movement vector field that directs the movement of any living organism from the ecosystem.

The movement under this context could be defined as information to use energy in the ecosystem to change the state of the current location " x " from A to B.

Therefore any life could be described by any isolated geometry from the ecosystem such that it could utilize energy in the location " x " to alter the state from A to B. The ability of the isolated geometry to communicate with the ecosystem as a whole such that it could interpret the movement vector field to align its movement through instincts.

The kind of movement information that any individual or isolated geometry could intercept or align could be defined by the geometric shape of the individual that specifically defines the movement structure of the individual.

24.3 The balance of intents

Suppose if the Ecosystem itself as a whole could alter its conscious intents such that the change of state occurs from A to B, then the movement patterns of each individual will need to change such that the new state could be reached.

This process could be defined by the " m territory intents " and the " n family intents " of each individual in the ecosystem and since the movement vector field is generated hierarchically from the top-down approach such that the " M terri-

tory intents " and " N family tree intents " of the ecosystem as whole branches off into " m individual intents " and " n family tree intents " for each individual.

Each individual could also interact with each individual in the ecosystem and a change in each intent could either be realigned, forced or destroyed with external force. This could create inertial forces in the movement vector field that could interact with the individual applying the external force to counter the effect depending on the stored potential energy driving the movement vector before the change of state with the external forces.

This is correlated to the rate of geometric change through the alignment of intents

24.4 Mechanics of each conscious intent could have the following metrics in the ecosystem

Observation of the current movement in the ecosystem relative to the location of the conscious intent. Specifically, this could described as:

Current State: At any time " t ", observe the locations of all the N individuals in the current state of the location" x ".

Target State: At the time " T ", the expected locations of all the N individuals in the target state of the location" x ".

Interaction: The ability to redefine the reallocations of all the individuals such that the movement vector field could be reset. This could involve the application of external force such that the changes in the locations occur and the magnitude of the force would have to be greater than the current force which is keeping the stability of the movement in the current state as a result of its accumulated kinetic energy and the stored potential energy that could be applied as another force if necessary to counter the external force being applied to change the state.

Experience: The ability to interact with information in the surroundings such the survival, nonsurvival, and reproductive needs in the surroundings are met. The actions that drive or energize the attention vector of the individuals such the movement could occur towards the conscious intents as a whole.

24.5 The conscious intent and the perception function

Suppose if each conscious intent could be defined by an individual, then the representation of the intent is a copy of his observation, interaction, and expe-

rience mechanics in a defined boundary of information.

A conscious intent that is set by an individual is defined by the following metrics :

The conscious intent is defined by " d " dimensions of information.

The individual that defines the conscious intent in a boundary could be defined as a collective consciousness that is associated with " m territory intents " and " n family intents " that express which pieces of information to observe, interact, and experience with the surroundings.

Each conscious intent is then defined as information for the movement vector field that connects all the local subconscious information fields with the global subconscious information field.

The conscious intent if introduced at a location will observe the related " d " dimensions of information, and interact with the individuals in the surroundings such that their movement trajectory is altered from the individuals such that their movement will be altered such that the conscious intent will be met.

Specifically conscious intent is information that describes the surroundings with the " d " dimensions of information such that the geometric shape of the surroundings is altered from the current state to the target state.

Therefore if the collective consciousness has " m + n " intents that is correlated to " D " dimensions of information, then if the collective consciousness is introduced at a location, then the collective consciousness will alter the surroundings using " D " dimensions of information from current state to the target state. This should result in the change in geometry of the location over a period of time while going from the current state to the target state.

24.6 The collective consciousness

Suppose a collective consciousness with " m territory intents " and " n family tree intents " could be defined by a conscious intent that is higher in the creation hierarchy (higher-order consciousness) that could have its own " M territory intents " and " N family tree intents ".

The ability to observe " d " dimensions of information in the surroundings could be correlated to the perception function which could be described as a mathematical function in the following format.

Suppose to detect the observation of " d " dimensions by the function, the perception function which is embedded in consciousness could be used.

Let there be " N " dimensions of information that could be perceived by the function

The conscious intent requires identifying the exact " d " dimensions of information such that the change of state from the current state to the target state occurs.

The change that needs to occur is a geometric change in the surroundings and the perception function needs to identify the exact " d " pieces of information that needs to be altered in the surroundings such the movement of the individuals in the surroundings could be altered to reflect that change.

The perception function identifies the location of the individual conscious intent relative to the other individuals at any time " t " and correlates it with various permutations and combinations of information such that the exact " d " pieces of data(information) are identified for the movement in the surroundings.

This process could be defined dynamically by repeated observation and comparison of data such as P(t), P(t+1),... and the exact combination of " d " that consistently predicts the pattern over the continuous form of observation over a duration T units of time.

The perception function could be imagined to be a sequence of boundary conditions that have been integrated into the perception function where each boundary condition observes the relative locations but with specific pieces or combinations of information.

Perception function P(t) could therefore have " X " number of ways to observe the relative change in locations such that each of the ways utilizes a unique combination from the set defined by the " NCd = N !/ d ! (N - d) ! "

Tracing the information trail over a period of time will identify the best combination of " d " pieces of information that describe the movement in the surroundings which then completes the observation of aspect of the perception function.

The perception function of the consciousness then manipulates the " d " pieces of information such that it could used to trigger the movement required to trigger the change in geometry defined by the conscious intent.

24.7 The energy for the conscious intent

Suppose if each conscious intent could be described exclusively through the perception function then the energy for the perception function is supplied by attention energy either by the observer consciousness of the perception function or another individual who has awareness of the existence of the perception function who could then provide his attention energy from his perception function which could then superpose to establish the conscious intent in any location at any given time.

24.8 Malicious intents

Suppose if there could be conscious intents that are specifically designed to alter the trajectories of the individuals such that energy from the individuals in the surroundings could be extracted from the individuals for longer durations of time T units, then the implication would be that their movement would be severely restricted to alter any change in the surroundings.

This creates a continuous flow of energy from the individuals in the surroundings to the creator of the conscious intent where the movement of the individuals is restricted or terminated and the total amount of usable energy is diverted to the creator of the malicious intent. This occurs because the attention of the individuals is fully diverted to the situation that has altered their movement and the source of that intent is the creator of the situation.

25 Extended Timeline Analysis

Let the family broader family tree at the current time " t " of individual A be defined as the shift in locations defined by the following mechanics :

Where the discrete boundary defined by the discrete points t-1,t,t+1, etc are defined by the amount of time " dt " that is defined by the amount of time at each location " xi " which could be variable depending on the intent at each location which could be broadly classified as " m " territory intents and " n family tree intents "

25.1 Observational AI bloodline analysis

The goal of the analysis is to determine the " m territory intents " and " n family tree intents " of the bloodline.

Individual A is located at a location " x " at a time " t "

The number of individuals in the interaction could be sorted based on the time spent such as:

Individual B - " P " units of time

Individual C - " Q " units of time

Individual D - " R " units of time

.....

Individual N - " Z " units of time

25.2 Regress the following criteria based on the above data by dimensional reduction

25.2.1 Defining deception

Estimated deception is where an individual has projected an intent at any location at any time (Any interaction) but the objective movement has diverged from the expected trajectory observed in that interaction.

This could be estimated based on the attention vector of the individual. If an individual has " n " objects or individuals in the attention vector in any

interaction then the locations where the individuals or the objects are located is likely to be the targeted destination of the individual from that interaction. However if the individual projects a target destination or location that is diverged away from the attention vector of the individual that could in theory be observed by various kinds of biological sensory perceptions such as the ability to perceive the energy trails of an individual.

From a more technological perspective, this could be determined by surveillance that records the movement of the individual. This could be defined as the rate of frequency at which the individual interacts. In theory, the frequency of the individual could either increase or decrease based on the attention vector of the individual and the assumption is that the movement frequency increases when the attention of the individual is directed towards any location that is the intended trajectory of the individual.

25.2.2 Estimated projected intents - Deception analysis

The average percent of time spent on deception from each of the above individuals such as :

Individual B - " p*P " units of time where p is between [0,1]

Individual C - " q*Q " units of time where q is between [0,1]

Individual D - "r * R " units of time where r is between [0,1]
.....
Individual N - " z* Z " units of time where z is between [0,1]

25.2.3 Estimated True intents - Objective movement analysis

The average percent of time spent on movement that does not diverge from the projection of intent.

The time distribution

Individual B - " (1-p)*P " units of time where p is between [0,1]

Individual C - " (1-q)*Q " units of time where q is between [0,1]

Individual D - "(1-r) * R " units of time where r is between [0,1]

.....

Individual N - ” (1-z) * Z ” units of time where z is between [0,1]

From the above analysis split the time distribution for EACH individual into the following set of criteria :

1. Mundane repetitive movement - Spilt by time percentage to eliminate

2. Unique movement - Split by time percentage as a regression variable

3. Repetitive movement - Split by time percentage as a regression variable

4. Random movement - Split by time percentage as a regression variable

From the above analysis, the following variables could be used to regress the overall ” m territory intents ” or the ” n family tree intents ” at each discrete location ” x ” defined by the duration of time spent .

In the present movement if the analysis is done then individual A is expected to spend the duration of time dt defined by the discrete boundary [t, t +1]

25.2.4 The regression variables are the following formation

These variables or the time distribution could either have an explicit or implicit relation to the other geometric movement variables which will provide several variations of intents depending on the best-fit approach.

Part 0) Deceptive intent analysis

Individual B - ” p*P ” units of time where p is between [0,1]

Individual C - ” q*Q ” units of time where q is between [0,1]

Individual D - ”r * R ” units of time where r is between [0,1]

.....

Individual N - ” z* Z ” units of time where z is between [0,1]

Mundane repetitive movements, such as showering, toilet breaks, etc. are ignored for analysis

25.3 Objective movement variables

The time percentage as a regression variable of the objective movement could be further split into three categories

25.3.1 Part 1) Unique movement variables

Individual B - " p1 *(1-p)*P "

Individual C - " q1*(1-q)*Q "

Individual D - "r1*(1-r) * R "

.....

Individual N - "z1* (1-z) * Z "

25.3.2 Part 2) Repetitive movement movement variables

Individual B - " p2 (1-p)P "

Individual C - " q2*(1-q)*Q "

Individual D - "r2*(1-r) * R "

.....

Individual N - "z2* (1-z) * Z "

25.3.3 Part 3) Random movement variables

Individual B - " p3 * (1-p)P "

Individual C - " q3*(1-q)*Q "

Individual D - "r3*(1-r) * R "

.....

Individual N - "z3* (1-z) * Z "

25.4 The goal of the analysis

The goal of the above analysis could be to do the following :

Split the timeline of the individual into " K " discrete locations where the amount of time that is spent in each location is defined by the duration of the interaction " dt " defined by the time boundary [tn-1, tn].

Apply the above analysis and discretize the time distribution " dt " into four categories as stated above

Identify sub-locations "xi" that could is associated with each of the discretized time distributions.

Estimate the intent for the time distribution of the deceptive intent with a collective reasoning model based on various hypotheses for the time distribution below:

25.5 Deceptive movement variables

boundary condition one: Assume as relevant to the collective analysis

boundary condition two: Assume as nonrelevant to the collective analysis

boundary condition three: Assume as partially relevant to the collective analysis (Y % which could be relevant based on probability . Suppose if it is assumed to be 50% probable then perform both, if lower than 50 % ignore or greater than 50 % assume relevant)

Unique movement variables

Repetitive movement variables

Random movement variables

25.5.1 Hypothesis for analysis from the dependent variables

Boundary conditions one, two, and three as stated above

Boundary condition four: correlation to the deceptive variables based on probability

Boundary condition five: correlation to other variables based on probability

The above comprehensive analysis of every discrete location that is part of individual A's timeline could be performed such that the overall collective " m territory tree intents " and " n family tree intents " of individual A's timeline could be deduced.

25.6 Family tree extension

Extending the time analysis backward in time the " m territory tree " and the " n family trees " could be traced to find the source of the intents by regressing the intents with more independent and dependent time variables from the network of family-free such that the source is traced to determine the exact divergence or creation of " m territory intents " the " n family tree intents "

Parent timelines of Individual A - The complexity increases with twice the variables mentioned above

Grandparent timelines of individual A - The complexity increases with four times the variables

Great grandparents timelines of individual A - The complexity increases with eight times the variables

....

However, the establishment of the connection to trace the " m " and " n " intents requires continuity of information such that it is either connected energetically through the attention vector or connected mechanically through the recorded trace of location information.

26 Timeline and Situational Intent Engineering

26.1 The definition of an individual's timeline

Suppose an individual A at any time " t " is defined by the amount of information that he has on his attention specifically in the following format :

The current time " t " in the location " x " where the number of the individuals that are draining his attention are sorted by the descending order such as :

Individual B - location " y " - percentage of attention as a function such that the movement of individual A is correlated to the movement of the individual. The higher the correlation, the higher the amount of attention measured in a duration of time " dt " where information exchange occurs.

.....

Individual N

26.2 The representation of the timeline

Let the individual's life be described as a timeline that could be discretized as various discrete points of time such as t-1,t, t+1, etc

Where the discretization occurs as a function of the location where the individual rests in any particular location such as :

t -1 , time spent = dt (deterministic)

location " X "

t, expected time spent = dt1 (forecast-able with reasonable accuracy)

location " Y " (assuming the current location)

t + 1, expected time spent = dt2 (forecast-able with lower accuracy because it includes another stochastic variable dt1)

Location " Z "

....

26.3 The forecasting errors for intent estimation

In theory, if the " intent " of individual A could be determined then the probability of accuracy of the variable " dt " increases because an algorithm could predict the amount of time, energy, number of interacting individuals, etc in each location that is accessible to the attention of the individual.

The implication is that at each discrete location which is assumed based on the actions that need to be performed in each location and the total amount of time for it determines the valuation metric of the actions.

The vice versa could also be true where if the amount of time that an individual spends at each discrete location along with the individuals that were connected to the individual through his attention etc, then the intent of the duration " dt " could be estimated based on similar analysis on the connected or surrounding individuals and an approximate distribution of each individual's time spend could be used to deduce the " m territorial " and " n family tree intents " and the collective information could be used to provide the probable " m " and " n " intents of the individual.

26.4 Situational engineering of the timeline based on unobserved time

Suppose the timeline of the individual could be traced back to the birth of the individual by the discretization model such as the one described above the model could be used to plot the same time distribution with a variable called observed and unobserved time.

Suppose the above graph could be replotted for individual A as follows :

t -1, time spent = dt

location " X "

The amount of time where the individual was not surveillance in one-way shape or form = x*dt

The amount of time where the individual was under surveillance in one-way shape or form = (1-x)*dt

t, expected time spent = dt1 (forecastable with reasonable accuracy)

location " Y "(assuming the current location)

The amount of time where the individual cannot be under surveillance in one way shape or form = y*dt

The amount of time where the individual can be under surveillance in one way shape or form = (1-y)*dt

t + 1, expected time spent = dt2 (forecastable with lower accuracy because it includes another stochastic variable dt1)

Location " Z "

The amount of time where the individual that could probably not be under surveillance in one-way shape or form = z*dt

The amount of time where the individual that could probably not be under surveillance in one way shape or form = (1-z)*dt

The goal of the analysis could be to increase the value of x,y, and z.

While the possibility of increasing the value of y and z exists because the action involves performing any kind of action now at the current time t or in t=1.

26.5 Engineering the past with information coercion

However possibility of increasing the value of "x" , creates a contradiction as the actions of the past could not be performed in the present moment. However, a principle of quantum mechanics could be used where the unobserved time of individual A could be assumed by the observing individual/s such that a new narrative could be created by using attention energy that has an effect on the quantum state of the unobserved time.

Since the observation is assumed at the current time " t ", and if a narrative is hypothesized by various groups of individuals by targeting any one or more outcomes for the unobserved time of individual A in the past, then depending on the amount of creative potential energy used, could create " k " intents such that it could get integrated into the " m territory intents " and " n family intents " of the individual at time t.

Since the unobserved time from any time before t , such as t-1,t-2, etc remains unobserved till now where the hypothesized " k " intents is driving attention energy from the observers, the intents " k " intents will either match or not match.

26.6 Mechanics of intent creation for the past

Suppose if there were two groups of individuals who had hypothesized had an individual narrative collective then, following the observation, the following possibilities arise:

1. The origin " K " intents of individual A will always be stochastic defined by the movement parameters observed by the observers. This will remain stochastic until no interference is made by the observers.

2. The origin " k " intents of an individual A could be made deterministic and defined by the observers. This could require an enormous amount of creative potential energy to shift the timeline of the individual because this changes " m " and " n " intents which is a function of the two independent but could be correlated family trees which in most cases could not be achieved because the amount of changes that required could change the entire movement flow vector in the territory thus changing the objective reality itself.

3. The origin " K " intents of the individual A will always be stochastic defined by the movement parameters observed by the observers. This will remain stochastic until no interference is made by the observers. However, if interference could achieved by by using the unobserved time as an advantage, it could done so by the following engineering process.

26.7 Establishing the triggers for the narratives to divert the narrative

Identify the sequence of unobserved time in each location " dt " units - Engineer narrative in the current moment " t " by assuming surveillance and creating doctored intelligence reports by engineering location and time stamps.

Then engineering the narrative such as :

At time t-1,

x*dt - engineer intent - plant location - time coordinated digital evidence - easily doctored with AI or other recorded surveillance establishing location at various times as collaborative evidence.

At time t,

y*dt - engineer intent - plant (location - time) coordinated digital evidence - easily doctored with AI or other recorded surveillance establishing location at various times as collaborative evidence.

Accumulate the evidence to doctor the situation through the process of situational and perception engineering where the individuals surrounding individuals could be manipulated by shifting the attention of the individuals towards various metrics that collaborate with the engineered intent.

The purpose of such engineered intents is to ensure that the destination of individual A from location " x " at time t to a specific location " y " at time t+1.

27 The movement vector field of the timeline

Suppose in a location " x " there is an established " movement vector flow field " that describes the rate of change of the overall geometry that occurs in the location " x "

The movement vector flow field is the GPS for the intuition of any conscious entity where powering the GPS requires attention from the average individual.

Suppose if there are " X " individuals such that they do not obey the intuition in the movement vector field such that they generate the movement vector field such that the average individual consciousness reads the movement vector field using their attention energy either consciously or subconsciously.

27.1 Generating the movement vector field over a territory

Suppose if an individual consciousness has " m territory tree " and " n family tree " intents that drive his attention vector for movement, the amount of energy that the individual could possess as potential energy could be correlated to the hierarchy of the intents.

27.1.1 Internal energy for the field

Specifically the exact conscious intent that branches off and eventually becomes the " m territory intents " and " n family tree intents ". In that context, the total amount of potential energy is expected to be higher if the hierarchy of the conscious intent is higher through the hierarchy of conscious creation. This could be the principle where no external energy is required to create the movement vector field as a result of the hierarchy of the energy source.

27.1.2 External energy for the field

The movement vector field could also be generated by absorbing massive amounts of energy from the surrounding population through their attention energy. This could be engineered in some context where events, information, or spectacles, or entertainment could be presented to the public either by overtly or covertly associating the mentioned process to one or more of the X masculines.

In such a scenario the attention that is drained from the individuals while being

associated with these events could be measured in time.

27.2 The transfer of energy

This process could then mean that if there are " N " individuals in the territory and if each individual spends 1 hour a day is associated with these events either by direct or indirect participation or simply spending time observing it, then a total amount of N units if time are dedicated to transferring energy from the individuals to the masculine who is associated with it.

Suppose if there are " X " masculine then the amount of energy that is diverted to various masculines depends on the hierarchy of authority of each masculine which in a literal context could be defined by the total amount of potential energy they possess at any given time " t ".

This is because the higher the total amount of potential energy that a masculine possesses, the stronger the movement vector field that is associated with the masculine. Thus the instincts of the individuals become correlated to the expectation of the masculine for his preferences for the rate of change of geometry in the surroundings. This is accomplished by literally by the trajectory patterns of individuals such that it could be analyzed by their time distribution on the following :

Survival needs

Non-survival needs

Reproductive needs

27.3 The change in the trajectory from the movement vector field

Preferences are altered by instinct such that the time distribution of the individuals changes with respect to the amount of time they spend with each type of individual based on their intents. The movement vector alters their attention vector such that they are diverted to the preference of the masculine which are reflected by the individual and his surroundings and the interactions occur to reflect the masculine intent.

The interpretation of this could be described with the interactions that occur in any geographical area and the location trajectories that arise for each individual at the end of the interaction.

Suppose if an individual seeks location trajectories at the end of each interaction, the kind of locations are determined by the individual's " m territory trees " and " n family trees ".

This could interfere with the movement field vector that redirects the individual's attention vector to the masculine's (m territory and n family tree intents).

In an energetic sense, energy is drawn from all the individuals such that it is diverted to the masculine movement thus establishing the territory based on his preferences.

27.4 The conscious awareness component

The difference between conscious and subconscious in this context could be defined by the conscious awareness of the individuals.

The conscious awareness could be further illustrated by observing relative movement in the surroundings and identifying the exact intent of the movement. In particular, the exact information that is driving the movement in the surroundings which could be traced by the number of things the individual has their attention on during their movement.

This could be understood as a movement that is occurring that is correlated to all the individuals or objects the individual has their attention on during the movement. Suppose if an observing individual wanted to alter the relative movement then it could be accomplished by altering the information or data that the movement is connected to energetically.

This could also be verified by the amount of attention or energy the individual spends trying to be associated with the selected objects or individuals energetically.

This component of the associated individuals or the masculines changes with the interruption of the movement vector field.

28 The simulation mechanics from interacting timelines

28.1 A boundary with one or more masculines

Suppose a shared boundary could be defined as the Earth Territory where the movement of individuals occurs according to the subconscious information field that drives the instinct of the individual specifically the attention vector of each individual.

The attention vector could be defined as the GPS of the individual that is quantum entangled to the authority structure of the territory.

The authority structure of the information flow for movement that occurs in the territory could be defined as the metrics of information that is observed in the surroundings and choosing one trajectory out of " n " trajectories available.

The metrics or the dimensions of information that is used for movement are defined by the masculine in the territory.

The definition of masculine is defined as the individual with the highest mass for his conscious intents " m " territorial and " n " family tree intents. The higher the mass, the higher the force the masculine could exert in his territory to alter or divert the movement of other individuals in his territory.

28.2 The interaction mechanics of conflicting masculines

The interaction could be further defined based on the target individual whose trajectory has to be altered. The mechanics of the interaction could be defined as the following :

If the individual is a non-masculine then the amount of force that is required could be minimal since the mass of the individual is assumed to be low.

If the target is a masculine or is grouped with other masculines then the accumulated mass of all the masculines could interact with the force established by the masculine to counter the movement-altering force. This could be because of the entanglement that occurs to coordinate the group's movement which could be affected if the trajectory of one of the individuals is altered. The interaction of the forces that occur between two or masculines to alter the trajectory of one masculine could result in an interaction of duration "dt" where the information exchanges that occur in the duration of "dt" is the additional work that needs to be done such that either the original trajectory is altered or remains the same.

The interaction that occurs over the duration of "dt" could therefore be described as a set of locations for the interacting individual. The interaction " dt " therefore alters the trajectory of the interaction of interacting individuals.

Suppose if the trajectory of the masculine remains unchanged and the trajectory of the target (and/or his allies) remains unchanged then, the force that could be exerted to explicitly alter the location becomes an agitated state of energy (free energy) if it is not directed by the masculine or the target masculine, it alters the location of the masculine and his locations of the authority in the substructure that is associated with the external force.

The reason that this occurs is because the definition of masculinity is the ability to alter the movement of all the individuals in the territory based on his current allies or collaborations.

The definition of masculinity is therefore defined by the perception function P(t) such that the boundary conditions that the function holds is the ability to observe information in the surroundings and correlate it to the relative movement that is occurring in the defined boundary or territory.

The more accurate the perception is, the relative movement of the surroundings could be estimated more accurately with the information in the surroundings. Therefore the function uses the locations of the data variables (information) that the individuals could observe as being correlated to the trajectory that the individual is trying to alter.

Suppose if the external force applied by the masculine does not alter the movement of the other masculine then the amount of control he has over the surroundings through his conscious awareness is reduced because the location of the observer and the other masculines will change implying the information flow that occurs from the masculine to the submasculine is no longer valid because of the contradiction observed.

The perception function of the masculine/s therefore readjusts the boundary conditions such that the best boundary condition to provide continuity for the event that follows occurs. This process then creates an update of information such the best boundary condition to realign the authority structure in the present moment such the local subconscious information field reconfigures in the various domains of the masculine territory.

If the target/s is proven to be the masculine then , then the " m " and " n " intents of the masculine that has been described in the local and subconscious information will take effect because it solves the information paradox of the perception function.

The interface that controls the information flow between the masculines through their event horizons to everything outside of it as a whole will readjust

the hierarchy of information flow to the territory from the masculines.

This is because the information flow from each masculine local subconscious information field and the global subconscious information field has to align.

28.3 The process of information flow restructuring

The process of leadership restructuring with the masculine occurs with the following :

The primary consciousness of the masculine that regulates the " m " and " n " intents through various other individuals is identified.

The primary consciousness has two components

Fifth dimensional awareness where the control over their domain over the location boundary (essentially a fourth-dimensional geometric region) defined by the coordinates (X Y Z t). For this fifth-dimensional awareness, the definition of time could be the exact direction in which the consciousnesses is observing and interacting with geometric regions. Regardless of the direction of observation, the interaction of the fifth-dimensional awareness changes the shape of the geometric structure.

The three-dimensional awareness where the fifth-dimensional awareness experiences the observation and interaction through the first perspective where the number of dimensions of information that are being observed and interacted for the fifth-dimensional awareness as a feedback loop could be used as a reference point or a node in the defined geometric fourth-dimensional structure of space-time.

This process which is common for all the masculine except the volume of the fourth-dimensional geometric region which is defined by the conscious awareness of the masculine. The higher the awareness of the individual, the larger the volume of control he could have for observation and interaction for the three-dimensional awareness.

28.4 The forced readjustment in the subconscious information flow field

The three-dimensional awareness of the masculine is clipped off from the fifth-dimensional awareness which provides the intuition for the movement of the node or individual.

This changes the instinct of the three-dimensional awareness such that it no longer aligns with the three-dimensional awareness as it is restricted by the amount of information that it could observe and interact with to plot the trajectory. The relocation of the three-dimensional awareness (node or individual) occurs according to the new trajectory set by the local masculine and conscious awareness will be readjusted by shifting his perception to the most probable narrative with continuity of information.

The fifth-dimensional awareness of the masculine however will be trapped in the time loop of projected realities such that until the " m " and " n " intents of the individual match the conscious intent outside of the time loop with the exact geometric actions required to align the conscious intent of the local masculine who had caused the contradiction in the perception. This is because the new masculine's trajectory may have defined various intents that may be contradictory to the old masculine and since the hierarchy of authority changed, the old masculine would have no control over his movement trajectory defined by his own free will or " m " and " n " intents.

The individual or the node may or may not have awareness of the interaction with his fifth-dimensional awareness and it could be irrelevant to the process.

29 The information flow mechanics

29.1 The flow of information towards the movement in the territory

The masculine in the territory has the attention in the following format :

1. The set " m " intents in the territory

2. The set " n " intents in the family tree

The source of energy to drive the movement could occur in the following ways specifically balance between the individual and the Ecosystem :

The ecosystem could be assumed to be an area that could be used such that the point consciousness could traverse from the point of observation which could start at the origin or any other consequent point in the area defined by the current state point o to the target state A and then consequently to the point B.

The balance of energy in the ecosystem could be defined by various metrics such as E units of total energy in the Ecosystem

The E units could total energy could be defined such that it could be further split by various segmentation such as the amount of free energy (potential energy) that the individual holds along with the total free (usable energy) that the Ecosystem holds.

E = U_ind + U_Ecosystem + X (Unusable energy)

The movement that occurs from one point to another such as starting from the origin to point A to another point B etc

Suppose the total amount of energy that could be used for movement while there are no other sources of energy available then , The total amount of free energy is used for the movement.

Suppose if the point is the only pointy in the Ecosystem the movement in the territory could occur by plotting forward trajectory by the masculine point from O to A to B and so on etc.

However, if the individual is plotting the movement without the conscious awareness of the ecosystem then the individual could have access to only U_ind units of energy for movement. The amount of energy then decides the other factors such as the velocity of movement, and the momentum that is generated with the forward movement. The forward movement is then defined by " n " unknown

objectives (family tree intents) which could even be as simple as " Exploration of the Ecosystem "

As the conscious awareness of the individual or the point consciousness could increase then, the movement that is occurring from point O to A to B occurs with the communication of the Ecosystem itself. The objectives of the ecosystem could even be as simple as " Exploration of the point consciousness "

Then the two trajectories are different such as :

Trajectory one

Point O to Point A to Point B

Total available energy = U_ind

Trajectory two

Point 0 to Point A to Point B

Total available energy = U_ind + U_Ecosystem

The masculinity is then the individual that could in theory override the decision of one over the other which is defined by the hierarchy of creation.

If the point consciousness is assumed to have been created first then, the conscious awareness of the individual is then defined by the boundary of his observation that he could do. In such as a case, the compliment of the point consciousness could be defined as the Ecosystem which is defined by the movement limits that the point consciousness could do.

The balance of trajectories could then be made by the following mechanics of the point consciousness :

Observation: The amount of information or the amount of data that the individual could observe in the defined area that describes movement or trajectories.

Interaction: The interaction with movement trajectory or the information/data such the movement trajectory could be altered based on the " m " and " n " intents implying the trajectory is one variation of the superposed intents for movement.

Experience: The experience part of the movement process could be described as the discretized cyclic movement of observation and interaction and the effect that it has on the movement trajectory. The effect that the movement of the trajectory has on the point consciousness could be measured in terms of the

amount of energy exchange that occurs to propel the movement trajectory of the individual.

29.2 attention vector and movement

Suppose the attention vector of the individual describes the direction in which the movement occurs, then this direction of the attention vector is regressed based on the Experience metric.

The Experience metric describes the the amount of energy exchange that occurs between the point consciousness and the Ecosystem, and the cause and effect of each discretized time step such as from point O to point B could have an impact on the total amount of free energy that is used in the total system.

This shift in the state of the total system that occurs with each time step redistributes energy such that the total amount of free energy that is present in the locally defined boundary of the point consciousness could change thus restricting or increasing the capacity for forward movement.

The more amount of energy that is accessible for movement, the movement of the point consciousness becomes more viable or " pleasant " for terms on Earth Territory.

29.3 Energy sources

If it assumed that the " n " intents of the point consciousness are driving movement then the energy that is driving the movement could be U_ind

If it assumed that the " m " intents of the point consciousness are driving movement then the energy that is driving the movement could be U_Ecosystem

Therefore the alignment of movement that occurs between the individual, the complement of the individual (the ecosystem), and the " whole " could occur in the redistribution of energy within various areas of the conscious awareness of the Ecosystem.

The whole could simply be defined by the total amount of Energy E units that could be transferred into other methods of movement as and when necessary.

29.4 The propulsion of movement and extending the theory to include other points

Suppose there is one point that could be the origin which will called masculine because it would be the prime that describes the entire ecosystem and the " whole " of existence.

The masculine starts of from point O to point A to point B ..... and after " k" such discrete shifts in movement.

There are " n " such point consciousness that are shifting locations in the exact same manner with the difference in their conscious awareness. Assuming these points were created after the masculine point existed and defined the entire ecosystem, then the points would not have awareness or information regarding the movement of various other points before its existence. As a result of this, the point-conscious awareness of the " n " point consciousness will always be lower than the masculine.

The conscious awareness in this context could then be defined as the movement information or the track records of movement that flows starting from the very first masculine point O till the current state of any of these " n " points that are shifting trajectories from one location to another based on their own set of " Experience " metrics.

At a random state of observation of the " whole ", the movement of any of these points occurs from current state O to target state A based on its own set of metrics that are defined as " m " and " n " intents defined by their own boundaries of awareness.

29.5 Energy transfer in the system

Each of these individual points could have the same format of free energy = U_ind

The total energy of the system is then defined as E = U_masc + U_ind1+....+ U_indn + U_Ecosystem (subtracting U_ind1+....+ U_indn) + X (Unusable energy)

The reason the amount of energy has to be subtracted as below from the Ecosystem is because

The masculine point of consciousness uses energy by removing free energy to create the " n " points which it uses for its own specific " n " intents.

U_Ecosystem (subtracting U_ind1+....+ U_indn)

Depending on the hierarchy of the masculinity of the point consciousness, the U_Ecosystem could be quantum entangled in the hierarchy of creation depending on which point consciousness could be interacting.

In theory, the free energy of any individual (U_indx) of any point could be part of the free energy of the Ecosystem itself.

Under these conditions, if the masculine point consciousness is interacting with " m " intents and " n " intents then the principle of least action for the transfer of energy occurs which may include the free energy of any one of these individuals.

The velocity or the intensity with which the energy transfer occurs could depend of the specific intent draining the energy and the hierarchy of point creation that is setting the trajectory for his " m" and " n " intents.

29.6 The variables for consideration

The variables that define the exact intent which could be defined by the attention vector as follows :

Current state O to Target state A - Primary attention energy being directed here

The experience metric - Specfic experiences defined by associations such as fixing other point consciousness to various other state changes from current state to target state.

Therefore instead of shifting location from point A to point B for one point consciousness which could be the masculine, There could be " N " such point consciousness that could be directed from their current states (x) to target states (y)

The more number of individuals that are altering states as a result of the movement directive of the masculine point consciousness, implies more amount of free energy used which could either be voluntary or involuntary for the non-masculine.

The hierarchy of the masculines defined by the hierarchy of creation represented concurrent circles

Suppose if the masculine at the point O could be defined by a boundary that describes his conscious awareness then by definition there could be " n " point

consciousness within his conscious awareness, then

there could also be a bottom-up approach that could in theory be valid as a probable state because if the point O itself could be one " n " point consciousness defined by another masculine Oprime.

Therefore the continuity of the masculine that occurs could be represented by the observer equation which allows the transfer of energy from the higher conscious awareness masculine to the lower conscious awareness of the masculines.

The lack of continuity that occurs as a result of being unable to perceive the dimensions of information outside the conscious awareness of each masculine results in the break of cause and effect of the continuous flow of conscious interactions which is essentially the constant creation of trajectories.

The contradiction of trajectories of various point consciousnesses that could occur between various masculine point consciousnesses and its subsequent " n " interacting with other points could result from the mismatched energy distribution that could occur between various regions for the forward movement of various point trajectories.

The higher the awareness, the more contradictions could forecasted or predicted according to a limit of information continuity for the " m " and " n " intents of each point of consciousness.

30 Information flow and observation

Let there be the top three individuals in the territory with the maximum wealth.

Let there be the top three individuals in any field of expertise who are the leaders in their chosen industry.

.....

Let there be N number of clusters of the top three leaders based on criteria chosen for the ranking or authority in the ecosystem.

Let there be a communication channel between the N clusters under the assumption that everything is deterministic in the ecosystem. The implication being that most cause and effect scenarios when it comes to the average day-to-day life of an individual is deterministically defined by another entity.

Under this assumption, there may not be an awareness for the individual of which one of his actions in the Ecostsem is :

deterministic

stochastic

If any action of the individual is deterministic, then the source of the deterministic action could be the following :

Internal instinct

External instinct

The ability to identify Internal and External instinct is achieved when conscious awareness of the self is achieved. The process could be achieved by paying attention to the instincts and the effect the instinct has on the self.

If any instinct initiates an emotional response, then instinct requires attention.

Caution when the threat levels are high - This instinct could be internal and part of the survival instinct

The External instinct - Suppose another individual in the surroundings had forced an instinct into the individual. This could be achieved by any kind of deception or manipulation. Therefore, this results in the situation where the external instinct could be disguised as an internal instinct.

30.1 The stochastic actions of an individual

Suppose the actions of an individual is based on free will, then his actions could reflect the unique signature of his behavior characteristics. This could be measured using the time distribution of the individual through the universal 2*2 matrix defined by the variables :

Survival needs - Nonsurvival needs

Comfort-Discomfort

The unique time distribution of any individual could hold the boundary conditions to measure the average territory health.

30.2 Illustration

Suppose if an individual's movement is recorded at any work environment, then the study of the individual's movement could be compared with his time study.

Suppose if any individual could analyze the recorded meetings of corporate individuals, then an AI algorithm could determine the comfort levels of the individual in the meeting. This data could be used to extract the source of the discomfort for the individual in the meeting. The source could be the :

The individual himself out of free will

Any of the x individuals in the environment.

Suppose if all of the recorded meetings of the individual could be analyzed, then the AI could analyze the interactions of all individuals in the workforce with the specific individual and the comfort and the discomfort of the individual with x other employees could be regressed.

This could be used as a reference to target specific individuals in the company for the situation engineering. The situation engineering principle is used when there is a need to create the simulation of free will concentration by diverting or limiting an individual's trajectory by deception.

31 The geometrical analysis of the self and surrounding of the ecosystem in a timeline

Let an individual at any time " t " is defined by the attention vector of the individual.

The purpose of the attention vector is to direct the movement of the consciousness toward any of its " m territory intents " and " n family tree intents ".

The intents in both cases define the purpose of the existence of the observing self.

Suppose if there is no territory, the attention vector is simply assumed to point toward the " n family tree intents ".

The family tree intents correlate to the existence of the observing self because the observer is assumed to be created for a purpose. The purpose is then movement towards the " n family intents ".

The attention vector could be visualized to be GPS system where if there are X potential pathways for the individual consciousness could gravitate towards them, the amount of energy for that movement must be a push from the point of creation of the consciousness.

The purpose of any consciousness creation must therefore be to push towards the " n family tree intents " defined before creation.

31.1 Geographical context

Let there be a point origin "o". The dimension and scale of "o" could be indertimante because the point could represent any anything in a subjective context. The only objective metric is the creation of another point P relative to the initial point of origin "o".

Suppose if o is in a void then the number of possibilities for the second point could be infinite because any possibility that could be the second coordinate could be represented in terms of relative distance such as :

Current state

point o

possible quantum states for point o in a void = n (could tend towards infin-

ity)

Target State

Shift location from point o to point P

Suppose if this is represented in a one-dimensional format, then the distance between point o to point p could be defined as the trajectory :

possible quantum state 1: Let there be an infinite set of possibilities for the locations of point P relative to o but they could be sorted based on the ascending order of distance between the two points as follows :

state 1: minimum distance - "d1" units - number of possibilities for the point P = n (should be lesser than or equal to infinity. This is because for a point in a void , another point could be placed any where on the circumference of a circle around the point.)

This is visualized as a trajectory between two points that could be relative to each other.

31.2 Expansion of trajectory

Let the number of trajectories that could be defined between these points is " K ".

Therefore the " K " trajectories to go from O to P could be explored for continuity by the following methord :

Out of the " K " trajectories which trajectory provides the best continuity through some sort of symmetry on a larger dimensional scale could be geometrically explored.

Suppose if all " K " trajectories are plotted individually as a constant state then the continuity that grows from the next hierarchical state could be visualized.

31.2.1 Illustration

Suppose Trajectory 1 was chosen for points O to P, sorted by the distance

Then the optimal path would be a straight line which is assumed to be trajectory 1 which also satisfies the law of minimal action.

Continuity from Trajectory 1

Suppose the next point could from P could be Q, then repeating the same process, the consequent derivative of trajectory 1 could be the trajectory 2 that follows the law of minimal action.

In this case, Trajectory 1 to go from O to P becomes deterministic, while the second generation Trajectory 2 becomes stochastic untill eventually made deterministic to determine trajectory 3.

31.3 Geometrical structures

The trajectories could collectivly form an enclosed structure that forms a " Z " possible set of structures that could connect the deterministic Trajectory 1 and several possible extension stochastic trajectories 2 that connects or intersects to create the " Z" structures.

Continuity from " Z " structures

Consider the first structure to be considered deterministic,

then adding another point " R " and repeating the process could then create " Y " structures for each possible variation of Z such that they could be assumed deterministic individually and create to create several stochastic extension structures for every possibility arising from the stochastic location of the point R.

The law of minimal action is the number of structures that could be made deterministic such that the further creation of more points could be explored.

Therefore geometrical structure optimality is defined by the ability to expand by creating and observing more stochastic structures where the intersecting points with the deterministic structure change with each new structure bieng observed.

31.4 The complexity

Suppose instead of creating one point at a time, there could be N points created at each state which branches into an infinite set of subsequent states that essentially creates quantum states defined by variations of the relative geometric locations .

Suppose if any quantum state is isolated to observe the geometrical shape could be observed as a frozen block of geometric shapes, the movement trajectories in the block could be frozen and this essentially implies observing the stochastic state as deterministic at which point movement stops or in theory time could stand still.

Then the geometrical shapes within the block could be altered and then be unfrozen such that the changes in states at various hierarchies of creation trajecteries starting from the singularity point o could be observed through movement.

This process of movement could be a deterministic code that literally defines the forward movement of all conscious entities with varying levels of trajectery control mechanics to alter the quantum states of geometry depending on the location and intersections trajecteries that are interacting.

Any entity under the geometrical context could literally be represented by a point conciousness and the location implies the relative distance between any point conciousness in the current state to the location in the next expected state.

Every point that is created could do the same process but with varying levels of trajectory control or structure selection depending on its current location and the intent to find the optimal trajectory or structure depending on its current location to avoid location contradictions and the corresponding geometric structures could be observed and analyzed for geometric continuity.

32 The creation of life in the multiverse

Let there be N individuals in the territory.

Each individual could be described as a conscious being at any given moment of time "t"

The individual has the following categories of forward trajectory for any day cycle (Ex. 24 hours)

Survival needs :

intent to eat, sleep, and reproduce

Non-survival needs :

Intent to create
Intent to observe
Intent to participate
Intent to control
.....

The possibilities for non-survival needs are infinite thus giving rise to the possibility of each intent taking life on its its own. For example, the intent to create is one of the first intent in the ecosystem, the intent to respect free will of other intents.

This allows for the possibility of each individual to represent more than one life form at a time .

32.1 Illustration

The intent to acquire power over other individuals - However the forward trajectory of this intent as it acquires power could be determined by its place in the multiverse.

Whether the intent aligned with the flow of creation or not, it could depend on the hierarchy of intents that preceded all intents.

The intent to create and maintain creation could be the intent that preceded most intents.

Therefore the intent that set this standard also known as the singularity tri-set of intents (creation, destruction, preservation) could be the governing entity of

all life if it was conscious.

32.2 The modern world of mini-intents

An individual on the territory of Earth lives his life (24 hours per day) in the following way :

The intent to own property

The intent to acquire multiple sexual partners

The intent to manipulate for control

The intent to help others

.....

The above intents could be classified as

Aligned with the flow of creation / Dharma - Balance Unaligned with the flow of creation / Adharma - Imbalance

The balance and imbalance mentioned above refer to the continuity of the original intention to create

32.3 Sorting the intents based on the population

Suppose if there are N individuals in the territory

X individuals have the intent to manipulate free will for control

In a functioning ecosystem if the value of X increases a certain point the ecosystem becomes toxic and the intent of the collective population aligns with Imbalanced interactions with the surroundings. This corrodes the interaction mechanisms between the N individuals and thus the flow of creation reduces.

Suppose X was large enough, then the intent itself could form a collective consciousness that is capable of coordinating each of the X individuals individually with a collective perspective for the forward trajectory.

Thus a new life form is born whose sole purpose is to manipulate other individuals for control and it will consciously govern each of the X individuals

independently.

In certain cases, this could be established by communication

For an individual who is living his daily life for 24 hours, if he adopts the intent to manipulate or control long enough.

The intent could grow stronger and in certain cases, the individual may connect psychically to the collective perception of the intent and exchange information or strategies to accomplish the intent.

This process of increasing awareness by inheriting the collective perception of that specific intent could provide a very powerful compass to navigate the trajectory such that the goal is accomplished.

In some cases, the collective perception of the intent could pair bond individuals who share the similar intent and a hierarchy is formed based on their skills and abilities who are subordinates to the original creator of the intent or any individual who has gained dominion over that intent.

An individual could have M such intents embedded into his genetic tree regardless of his awareness of the intents.

Thus one random individual is living M lives, each of which exists in a different dimension of observation although some may intersect.

32.4 Manipulating intent as a defensive or offensive mechanism

Since each species evolves its consciousness in unique ways where the biological forms are structured to provide information, the kind of information that a species needs for its survival could vary according to species.

For instance, the homo sapiens species could require verbal or non-verbal communication to implant or introduce intent into other individuals.

On the other hand, a random species could have evolved with direct intent communication as a result of their biological systems.

The implication being that no amount of time is needed for verbal communication although occasionally non-verbal gestures could be used.

If multiple species interacted then, then direct intent communication would be the most efficient form of communication as it would bypass any language

and time barriers. The intent communication could be instantaneous

The process assumes that the conscious capacity of intent communication would be higher for one over the other as it is the case most of the time.

32.4.1 Sequence

Inplant intent from dominant species to the other

Gain consent by deceptive practices

Abuse of evolutionary hierarchy to enslave or destroy

Inplant ideas, directives, etc

If a skeleton crew from these species organized themselves under an umbrella (projected) intent to hold dominion or enslavement of an entire territory on Earth, then they could establish an entire socio-economic planetary governance under this agenda where the intent is to strictly control the individuals at various strategic locations in the territory.

The skeleton crew could then have their own social leadership structure based on their skills and ability to maintain authority in the territory.

The native population could then be harvested for time and energy purposes if their consciousness who are prone to manipulation as a result of their developing conscious awareness.

32.5 The continuity of life for an average individual of any species

Let an individual A be responsible for the creation of Y intents during his lifetime on Earth

Let there be Z individuals who have adopted one or more of these intents

The continuity of A's life could be achieved as the collective perception of Y intents he created. If the Z individuals have adopted the Y intents voluntarily or involuntarily, then the collective perception of A could start applying external force to gain more conscious control of the Z individuals.

Therefore as the original intent of individual A merges more and more with

the Z individuals the personality of the A becomes more and more infused with the Z individuals whereas in some cases it completely takes conscious control over the Z individuals.

In this context, the life of the individual is defined by the number of conscious intents he sets in the trajectory which is carried on through consciousness genetics.

33 The Timeline Intersection Strategy

Let there be " N " individuals in the territory

Let there be " x " masculines in the territory

33.1 Simplified Timeline

Suppose there was a timeline of individual A that could be described by the following information (or time series)

t = - dt

Location = " x "

Primary attention metrics

Secondary attention metrics

The above metrics are defined by each individual consciousness specfically what drives the attention vector of the individual for its movement from one location to the next.

t = 0

Location = " y "

Primary attention metrics

Secondary attention metrics

t = dt

Location = " z " where z = z1 or z2 or z3

33.2 The trajectory plotting from current location to the target location

Suppose Individual A at the current moment (t = 0) is located at Location" y " and the trajectory of individual A will depend on the interaction in the current moment that occurs in the interaction of duration dt.

Suppose an individual has to traverse to a new location at time t = 0 , then

the interaction that occurs in the duration of dt units directs the location at t = dt depending on the priorities defined by the primary and secondary attention metrics .

Since this could be a variable or a stochastic or a deterministic choice set by the attention vector of the individual, the following parameters could be considered.

At t = dt, if the individual chooses his trajectory to either z1 or z2 or z3 then there are three probable states for the timeline of the individual.

The probable states are a function of the primary and secondary attention metrics however the exact location where the trajectory could be set for t = dt could be variable as well.

For instance, if the linearity of time could be ignored then the decision to choose the Location " z " at t = dt could either occur at t = - 4 dt or 4 dt

Where the implication is that the choice to choose the exact location at t = dt could either have occurred in the past or in the future.

33.3 Interaction of two masculine timelines

Suppose if the target destination for individual A could be at Location " z1 "

There could be another individual B such that he could apply an external force at the current moment t = 0 such that the trajectory of the individual could be diverted to the Location " z2 " or " z3 ".

This process could be accomplished when individual B could introduce an Event or an individual into the primary or the secondary attention metric of the individual such that the perception function of the individual will be forced to consider the event or the individual in his attention vector to plot his trajectory.

The event of the individual who serves as the manifestation of the applied external force by individual B . Under this assumption, the individual or the event has an intent that is forced into the current moment t = 0 at location "x ".

The trajectory of the individual could have momentum for his trajectory as it traverses from one discrete location to another.

This new external force that is introduced into the interaction in the current moment could either serve as an alignment force or an opposing force to the

trajectory of the individual which is estimated to be z = z3.

Since an individual has an intent for every event or individual that is in his primary or secondary attention metric in any interaction (at any location) , it could be assumed that the conscious intents could serve as a vector with a magnitude and direction that is driving the movement from the current location " x " to the target destination " z ".

33.4 Contradictory projection of intents

Suppose if the external force that is applied by individual B creates choke points in a linear sequence that serves as attention triggers such the overall intent that is driving the movement from " x " to " z 1" could be slowed or altered completely, then the principle of deception could be applied in the following manner.

The event or the individual that is introduced as an external force to the attention vector of the individual could have a projected intent such as individual A assumes the purpose of the external force is an alignment aid rather than conflicting aid.

In such a case , the conscious intent vectors that is driving the forward movement from " x " to " z " will have two perceptions for the movement that could occur.

Therefore two contradictory perceptions will drive the forward movement as a result of individual A having his attention on an event or individual that is covertly plotting an alternate trajectory for individual A. This method of deception includes the association of the external force in his timeline for the conscious decision-making from one location to another. This could then in theory reajust the probabilities for z1 or z2 or z3.

On the other, if the exact description of the external force could be identified by the individual by decoupling the true intent of the event or the individual introduced would allow the force to be commanded by name (a relative movement that is occurring with a purpose. identification of purpose via discernment will establish masculinity in the local subconscious information field which will allow to redirect the vectors affecting the location trajectories to align with the global subconscious information field which is interfaced to the masculines intent by authority)

In this case, the redistribution of the probabilities for the target destination such that both conscious intents will contribute to maximizing the destination " z 1 " could be accomplished by commanding the vector to act on the point of origin.

The magnitude of the force from each conscious intent could be directly proportional the magnitude of the external force applied by individual B as an opposer or individual A as an intent.

In such a case, the external force will be applied to individual B such that his resources could be used to boost the intent of the individual by altering circumstances to boost the trajectory.

33.5 The consciousness management system

Suppose if an individual's consciousness could be described as a location reference similar to a GPS system where the attention vector of the individual directs the movement of the individual .

Suppose the attention vector of the individual is naturally aligned to the " m " territorial intents and " n " family tree intents.

The mechanism of the location reference and the intent could be engineered in the following manner.

Suppose if individual A has " n " individuals in the conscious awareness of his consciousness and at any given time t = 0 (current movement) ,

If the location of individual A is assumed to be the origin which in this case is assumed to be " x "

The conscious awareness of the individual could then be described as all the locations (assuming X = number of locations) that the individual could access through any means which could be sorted based on the probability of reaching that destination in the next discreet time step t = dt.

Then the location of the " n " individuals which could be located in any one or more of the locations.

The distance between the current location " x " to " X " and other possible locations could be described geographically as the following :

Let there be another random number " K " which describes the number of possible pathways or trajectories that could be used to reach " X " destination points.

Out of these " X " trajectories, there could be three destinations that are most probable such as:

” z1” - Favored by individual A’s timeline

other - Favored by individual B’s timeline

33.6 Applying the law of minimal action to estimate optimal pathways

The trajectory probabilities are determined by consciousness based on time, and energy which is deduced from the distance estimation based on the current relative locations of the ” n ” individuals at any instant of time t.

The optimal path to traverse from ” x ” to each one of the possible destinations in the subset X = z1,z2... could be the shortest path to get from

” x ” to ” z1 ” - Estimated distance d1

.....

” x ” to ” zn ” - Estimated distance dn

Where there could be multiple trajectories but in each of the above cases but it is assumed that the subset d = d1,d2... contains only the shortest or the optimal path. The assumption here is that the shortest distance implies that the least amount of time and energy is needed to travel to each of the possible trajectories in X = z1,z2,

The above process could be intuitively estimated by the perception function of the individual consciousness who is traversing from the current location ” x ” to the target location ” z ”.

33.7 Estimating the quantum state of locations

Suppose the individual consciousness has a set of intents at time t = 0 such as I = m1,m2...n1,n2 then the exact trajectory that is chosen for the target location ” z ” will be based on the optimization of the process of the Intent set I which could be assumed to be a superposed state of the individual at a time ” t ”.

This superposed state could be defined by the perception function P (t) of the individual which uses the various boundary conditions to correlate the information in the surroundings and the correlation of the information to the relative locations of the ” n ” individuals in the surroundings.

The boundary conditions allow to observe the relative location of all " n " individuals relative to the observer location which in this case which is location " x " which is assumed to be the origin and identify the exact information that is driving the movement.

The higher the accuracy of the boundary conditions of the perception function the more accurately the exact pieces of information driving the movement could be identified.

In other words, this implies identifying the intent of every one of the " n " individuals accurately and the more accuracy there is , the more predictable the movement of the " n " individuals towards their own future trajectories.

In terms of stochastic estimation, there could be " Y = y1,y2... " possible pathways that each individual could take and thus the total number of trajectories that could be forecasted by the individual consciousness could be defined as n * Y.

There the trajectory that is plotted by the consciousness of individual A has to account for the forecasting of n * Y trajectories that could be plotted.

Suppose then each of these trajectories could be discretized further as the following :

Let the total number of trajectories to be forecasted be " Q = q1,q2,.... ". Each trajectory q1 could be split across by the following discretization of the trajectory

33.8 Forecasted trajectories for analysis of the movement of the " n " individuals

Assuming that all the trajectories could be observed simultaneously regardless of who is taking the trajectory.

Trajectory of q1

t = 0

location 1

t = dt

location 2

....

Trajectory of qn

t = 0

location 1

t = dt

location 2

....

The masculine individual A who could in theory observe all the trajectories as quantum states defined over the boundary could take any random trajectory such as :

At t = 0 ,

take q1's choice of trajectory for location 1

At t = dt ,

take q4's choice of trajectory for location 8
etc.

Under this context the total number of possibilities for the movement of individual A for his movement trajectories is a large set of locations such as :

Location quantum states L = L1 , L2,. ....

Where

L1 - All the possible locations that are stored in the forecasted quantum state Q that could be used as the location for the first time step t = dt

....

Ln - All the possible locations that are stored in the forecasted quantum state Q that could be used as the location for the last time step t = n* dt to reach the intended destination " z1 ".

34 The Situational Timeline Engineering

Suppose the timeline of an individual could be traced through the recollection of various instances of interaction through a photograph which could in theory be defined through the sequences of events such as as :

34.1 The Timeline

Let the individual A be defined through a set of observed data such as :

At t = 0 ,

Interaction with " n " individuals that could last a duration of T units

Let the number of observers of this event be " x "

At t= 0 + delta t

An event such as the consumption of food and alcohol

Let the number of observers of this event be " y "

At t = t + delta t

A meeting with " x " set of individuals

Let the number of observers of this event be " z "

.....

At t = T ,

Where T is the current or any situation that could be defined as T = E [t]

Let the total number of observers be " N "

Then the timeline defined from t = 0 to t = T has several perceptions or the subjective reality defined by the above objective reality of the time series,

The total amount of energy that the timeline is receiving through the total amount of attention that the timeline or the masculine of the individual is receiving. The attention energy therefore describes the sequences of events with the superposed cause and effect that could be associated by the various sets of

observers that could be observed as

The observed movement of the individual could be summed up with the intent matrix such as :

Projected intent - The amount of time "individual A" interacts with various data points such as :

Survival needs

Nonsurvival needs

Reproductive needs

Let there be " M " assumed or expected causes for the cause and effect of that movement that could also be assumed as intent depending on the perception function of the individual./s

Objective intent - The true intent of the individual which could be relative depending on the interacting observer of the timeline

Let there be " N " assumed or relative cause that could be true depending on the perception function of the individual./s

The timeline of the individual according to the observer equation, therefore, could be an expected number of possibilities " M + N ".

The subjective reality that could collapse into objective reality (The exact consequences specifically the rate of geometric change that occurs at any point of observation . In theory, it could be possible that various groups of individuals could observe interactions that could potentially diverge through the aspect of assumed purpose or intent specifically identifying the cause and effect that are interacting in the timeline.

This process creates a contradiction in the endpoint of the objective reality defined by the perception function of various individuals when observed independently

The amount of energy that is going into any observation depends on the conscious awareness of the individuals and under normal circumstances " cause and effect " of any movement could be pinned to the purpose or intent that could be defined by the individual/s that has a high amount of attention from various interconnected groups of individual.

34.2 Situation engineering of the timeline

Suppose the projected intent could be used as a tool to engineer the timeline within perception engineering where at each discrete point t of the timeline one or more forced interactions could occur such that ,data points could be triggered through objective movement tracking such as the captured interaction with " n " individuals and/or T units of time recorded which is then labeled based probable timeline that is balanced on balancing the probabilities of intent.

The information that is stored based on all the data collected through the balance of probabilities could, in theory, be defined by data points that could be defined that could be assembled, sorted, and organized such that :

One collection of identified points that describe intent as " x "

Another is " y "

....

Thus the timeline of the individual has m*n subjective realities where the above method is based on the balance of probabilities such as x,y, etc.

Two metrics could be of consideration,

The total amount of energy that is going into x or y which could have multiple sources or masculine.

34.3 Weaponizing data-powered movement or outcome control

The above process could then be used for weaponization purposes where a sequence of projected intent triggers could then be used to establish the end point t = T of the timeline of the individual.

34.3.1 Consciousness remapping

Since this process breaks continuity with local and global subconscious information fields contradictions occur at various discrete points of time such the objective reality could change for one or more of the observers with contradictory when the collective intent is established by a higher amount of attention energy, The discontinuity occurs when two sets of masculines have a contradictory intent for each of the groups of the masculine and the superposed intent

which is realized has either " x " or " y ".

The discontinuity occurs when intents are assembled by any individual consciousness by losing track of the relative locations of the surroundings of the observers or other interacting individuals. This process results in the timeline shift of the individuals from the masculine timeline to NPC timelines where the amount of control over the surroundings reduces the conscious awareness of the individuals.

This is because if the superposed intent has " x " as the cause and the individuals who had intended " y " to be the cause will be shifted into a new reality where " x " is the cause.

This implies the masculine or the set of masculines that had forecasted or manifested the timeline with " y " as the cause for projected intent, will lose their masculinity in the supposed timeline which is an indicator of the loss of ability to control variables in the timeline.

34.4 Potential energy and the kinetic energy of the timeline

The timeline of individual A could be directed by a " k " set of individuals including the interacting observer.

Let the amount of creative potential energy used throughout the process could be defined as the " P " where the individual A interacts with the surrounding individuals through various forms of movement.

Let the sequences of events where individual A has supplied various forms of energy to his timeline will start to accumulate momentum in his timeline. Since kinetic energy accumulates with the increasing set of alignments, the flow of the timeline starts to gain momentum (M) along with the kinetic energy (K) of the timeline.

Since both parties who either want " x " or " y " as the outcome of the timeline of the individual, the variables M, K, and P from conflicting sides are evaluated for the superposition of the timelines where the weights of each individual's attention will be superposed into the resultant timeline.

34.5 Karmic Timeloop is defined by the natural law of conscious creation and territory expansion

The losing party from the conflicting outcome, would then have to redefine or restart their conscious awareness process according to their new timeline which may or may not have the same set of rules for awareness growth. In another sense, the point consciousness of each of the individuals will redefine their geographical locations that are best suited for the readjustment of the conscious awareness in the surroundings by literally relocating their locations based on their intent at time t.

If the losing parties then start interacting in the new timeline based on their established outcome then their locations will be adjusted to reduce their impact on the purpose and intent by literally forcing their locations. In other words, the time distributions of such individuals will have lesser and lesser variability according to the interacting observers themselves .

This process could in theory be defined as " Timeloop " where the individual interacts in the established boundary based on his new weights that define his impact factor to the new timeline.

The time loop occurs because the individuals no longer align with the resulting timeline and their actions could be blocked off from the new masculine superposed timeline as it violates continuity through the event horizon of the time loop. In such a scenario, the consciousness of the individual either introduces or observes new boundary conditions such that their intents that are blocking their forward movement in their own timeline.

Such time loops could be assumed as a defined time period from their own timelines based on their " m " or " n " intents such that the keys to get out of the time loop or " karma " lies in the exact sequences of interaction in the time loop that needs to occur such that event horizon of the time loop will disappear as the packet of time merges back into the superposed timeline outside the time loop.

35 Synchronicity Forward and Backward in a Timeline

Let an individual be defined by his lifetime of T years

The lifetime of T years could be described as time spent under the following categories :

Growth cycle

Reproduction cycle

Reflection cycle
Time spent in the growth cycle of the individual (T/3) years

Time spent attached to "x" individuals from the following categories

Family

Friends

Sexual partners

.....

The timeline of the individual during the growth cycle could be described in two directions :

The path forward in time

The path backward in time

The need for the two directions is to determine if the pathway of the individual is deterministic or stochastic. If the timeline is split in two directions, the synchronicity in the intent of each interaction could be determined in two directions simultaneously

The need for the comparison in two directions is to determine the primary intent of the timeline in both directions.

If the intent of each interaction is traced backward in time through each interaction, then the intent could be assumed to be deterministic. This implies the accumulated intents from each interaction form the primary intent of the individual, which could be defined as the boundary condition of the lifetime.

35.1 The boundary conditions moving backward in time

The boundary condition of the lifetime is defined by the movement of the individual in the territory further defined by :

Sub intents with " x" individuals throughout the lifetime at specific locations relative to each other. Thus, there are three variables :

number of individuals met during the lifetime = n

the amount of time spent with each of the individuals = interaction time = d = d1,....dx

Sub intents with " y" individuals = stochastic

Therefore, the lifetime of the individual in boundary conditions is defined by the following boundary conditions :

The number of individuals met by primary intent = x

The number of individuals met by stochastic intent = y

The amount of time spent with "x" individuals = X years

The amount of time spent with "y" individuals = Y years

X + Y Years = T years

35.2 The boundary conditions moving forward in time

To simplify the intents of the individual, it could be assumed that the individual could have an intent, and there is resistance from the surroundings towards the intent.

This could be simplified and expressed in the following ways :

Factor to consider- The Primary intent of the individual towards his surroundings as a whole

The number of individuals met towards/pursuing his primary intent = x

The amount of time spent with "x" individuals = X years

Factor to consider - The Primary intent of the surrounding towards the individual as a whole

The number of individuals met towards/pursuing this primary intent from the surroundings (resistance or inertial towards his intent) = y

The amount of time spent with "y" individuals = Y years

X + Y Years = T years

If the intents are equated and the variables are compared, x,y, X, Y is compared then synchronicity could be observed in both directions for major invents for an individual's lifetime.

Suppose if there are "p" positive events and "q" negative events during his lifetime, then the synchronicities could be mapped by discretizing each interaction with each person as a whole and plotting the three variables :

Time with x individuals could be sorted by time distribution in descending order

Time with y individuals could be sorted by time distribution in descending order

Thus, the top three individuals favouring the primary intent of the individual could be determined.

The top three individuals resisting the primary intent of the individual could be determined.

36 defining timelines

36.1 The origin of Karma - Interaction of an individual with his surroundings as a whole

The karmic relationship could be the process that allows for the balance of free-will interactions made by conscious creations.

The interaction between two individuals is defined by time.

Calculation of forces between positive and negative energy could be done by applying a balance of forces at each interaction. The symbiosis between an individual and the surroundings (any one individual) could define the purpose of the individual to the surroundings.

36.2 Defining Timeline

Suppose the timeline for an individual A is defined by the number of individuals he interacts with with the following information :

The primary intent of individual A

The primary intent of all the other individuals in the vicinity for individual A

Therefore the Timeline for any individual is the result of conscious free will intent by an individual and all the individuals he chooses to interact with.

36.3 The purpose of the timeline

Suppose if an individual has a primary intent then he navigates the map towards the primary intent. The path could be described as the description of individuals and the interaction durations to fulfill the primary intent.

The timeline is therefore directional and towards an intent. Each intent has a particular route that starts with a specific group of individuals in the surroundings.

The interaction will either expand the timeline to further the primary intent or suppress the primary intent of the individual.

If the timeline expands then the locations of other individuals are observed

and the timeline is extended toward the primary intent.

The timeline then continues to the next stage where it reaches the next stage of the primary intent or ends.

36.4 The intersection of timelines

When individuals interact for a few hours, their timelines merge for a few hours

The merging of timelines which are the result of the details of each of the perceptions that is available to each individual consciousness in the interactions.

Since every individual has a perception that is shared in the interaction, the merging of the timelines occurs with the projected details only. If the projected details are an illusion, for instance, an interaction started under a false intent, the distortion in perception occurs in the surroundings as a result of the masculine primary intent of deception.

36.5 The backstory for the timeline changes

Each timeline or timeline for any individual defines the cause and effect of objective reality between individual A and the other individuals.

When two individuals interact and merge their timelines, the resultant time is formed by adopting the specific details.

The specific details are interpreted through interaction rules for each of the individuals that is defined individually or culturally applied in each interaction.

36.6 The flow of timelines

The timelines for any individual is a dynamic process and depend on the number of perceptions he has over the objective reality.

The individual has to discern which timeline he is currently in the current moment by observation.

The interaction is then based on the timeline which defines the relationship between individual A to the other individuals in the interaction under the current timeline.

36.7 Friend or foe based on intent

Since the timeline changes after each interaction, there could be individuals who are friendly in one timeline and hostile in another.

At each current moment, every individual that an individual A is interacting with could be friendly or hostile based on the following metrics :

The individuals in the interactions

The collaborations between each individual and between each other

...

36.8 Sharing selective intent for interactions

The desired timeline is accomplished by navigating individual to individual based on authentic interactions.

The objective reality for any individual where his instinct is the driving vector for his attention

The objective reality is defined by the cause and effect of the masculine/leader in the territory

Let one individual be masculine where he directs the actions of the other individuals in the vicinity. The interaction of the individual with the other individuals in the surroundings could be represented by a point of conscious intent.

36.9 The origin of conscious intent

The point of conscious intent could be grown in individual consciousness within a boundary to perform tasks such as the transmutation of any negative force acting on it to a positive one).

The grown intent could be a property of certain kinds of consciousness that includes a multitude of perceptions. The higher the points of view on any desired topic, the more accurate the understanding of the objective reality.

There could be a primary intent to the consciousness which is to transmute or engineer the creation trajectory on Earth's territory.

The probability of this will be maximized with the flow of information necessary to transition to the next phase of human evolution that branches off into three ways.

36.10 The duration of life

Suppose life is an ever-expanding duration of conscious observation and interaction that lasts a duration of T units.

The process of birth and death could be limited to one lifetime however assuming consciousness is continuous till the primary intent of the consciousness is fulfilled or opposed yields a new duration.

This could be assumed to be similar to the first law of motion however it is applied to the primary intent of the consciousness.

Suppose the primary intent of an individual is adopted as an intent from other individuals, the primary intent is kept alive by all the individuals who have adopted the intent.

Thus the process of conscious life has a different duration of existence than a biological life of existence.

37 The timeline map

Let an individual be defined by his lifespan of T years. The time distribution of the individuals could be defined explicitly in terms of their interactions.

The lifespan could be split under the dimension of interactions. The entire duration of an individual's lifespan could be split as intersections such as:
The interaction time spent with own's company (Observation or interaction with the self)

The interaction time spent in interaction with Individual A

The interaction time spent in interaction with individual B

....

The interaction time spent with individuals A and individual B

.....

Where Individual A, Individual B.... could be anyone from a parent, colleague, friend, sexual partner, etc

37.1 The purpose of the lifetime

Let the individual have a primary intent for his lifetime of T years.

The primary intent is the chosen pathway for the duration of his time based on free will intuition

37.2 Defining the surroundings

Let the individual's habitat be called the ecosystem. In a specific coordinate, the ecosystem could be labeled as Earth Territory with 7 sub-continents.

Let there be N individuals in the Territory between the territories.

37.3 The representation of interactions in the territory

Let each individual interact with other individuals which could be summarised as data based on interaction time sorted and arranged in the descending order of the total interaction time. (similar to the first section)

The interactions between the individuals are based on the learned rules of interactions observed from the surroundings.

37.4 The learning information flow

Suppose if the parents are the individuals that spend most amount of time with their offspring then the intents of the parents are transferred to the offspring as genetic material.

If the intent is defined as one of the reasons consciousness exists, then the intents are transferred from the actions of the parents.

37.5 The lifetime interaction tree

The actions of the parents are defined as the rules of their interaction for their surroundings, then it could be described as the following :

Interactions with family group :

Interactions with friends group

....

An individual observes the interactions between each group during the growth cycle and learns the mechanism of interactions for the following :

- Declaration of intent for the interaction

-Level of authenticity maintained which is defined as the accurate declaration of intent for interactions

-Nature of collaboration

-Nature of competition

All of the above depend on " n" number of intents each individual has at any

point of time.

37.6 The correlation intent declaration and purpose

Every interaction has a mathematically optimal solution which is the exact matching of intents from all the individuals in the interaction.

If intents are assumed to be deceptive then, the probable intents for any interaction could be described in a matrix form.

37.6.1 The primary intent of an interaction

Let the number of individuals in the interaction be N

There are (N + 1) intents that could be functioning in any one interaction.

Suppose the intent for the interaction is set by Individual A

The intent is publicized as "x" by individual A

The actual intent or the true intent of Individual A be "y "

The intent for the interaction from each individual be "z " assumed to be similar or random

....

37.7 The optimal path for an individual in the Territory

Suppose an individual has a lifetime of T years and he engages in M interactions during the lifecycle.

If x is declared as the intent by the individual in every interaction, the duration of each interaction will reach its optimal length with will be a minimum.

This is because the intent of any intent is genuinely declared in every interaction, and then the amount of time spent on the deception of intent for any reason becomes zero. This maximizes the amount of time spent which is suitable for the intent of any individual.

This is because if interactions occur with no deception, the information shared will assumed to be accurate and defined as objective reality or truth. This measure maximizes authenticity in every interaction eliminating the need for deception of intent.

37.8 Leadership and deception of intent

If the primary goal of leadership involves deception of intent, the purpose of deception of intent will define his eligibility in the leadership role.

Since authenticity involves frequent conflict and aggression in any sort of form available, the leadership could potentially engage in aggression tactics in leadership interactions.

The following metrics will redefine management and governance :

Deception of intent - Based Interaction rules in any ecosystem which is based on time-free will morality laws.

Aggression management - Tolerance to aggression from other leaders and the ability to display the required level of aggression according to the situation.

Discernment / Deduction of intent - The ability to deduce the intent of any interaction assuming there is deception. This could be further expanded as deducing the nature of each intent from each individual in the interaction.

37.9 The Ecosystem response

Suppose an individual is part of an ecosystem with "m" other individuals.

The interaction mechanism could be personalized with the binary mechanism of sorting interactions.

Interaction of individual with the ecosystem (includes all interactions combined with other individuals)

Interaction of the ecosystem with the individual

For the above two perceptions, the balance is met with the duration of the interaction which is the objective reality.

For an individual with a lifespan of T years, the objective measure of his inter-

actions with the Ecosystem is the duration.

The purpose and intent of the individual are assumed to be the conflicting goals whereas the intent is the free will of the individual. The purpose of the individual is always external to the individual because creation is a conscious process and occurs when necessary.

On the other hand, the purpose of the individual could be described as the intent of the Ecosystem for the individual prior to birth. For example, the parents who are part of the ecosystem will create offspring for a purpose either to continue genetics, family intent/purpose, etc.

If the free will intents of the ecosystem and the individual is not met with a balance, then the imbalance will be reversed by redefining the purpose of the individual by the ecosystem.

The free will between an individual and the ecosystem could be described as the free will to choose locations and actions at any point of time.

In practical terms, this implies that the conscious control of an individual in his territory becomes harder.

38 The GPS of consciousness in the time dimension

38.1 The lifespan of an individual

Suppose the lifetime of an individual A on Earth is defined as T years.

Suppose the life pathway of individual A is defined by the individuals in the surroundings with whom interactions may occur with individual A.

Individual A has a primary intent set by his free will and he continues to interact with individuals who align with the primary intent.

38.2 The interactions and timeline branching

Let each interaction be defined as a duration of time d units (random number depending on the nature of the relationship)

Let interaction have an intent that may or may not be known to all the individuals in the interaction.

Let each interaction for individual A result in x trajectories or pathways that branch from the intent of the interaction.

38.3 The location inference

The primary intent of a lifetime for an individual has a direct correlation with his location distribution at various times of the day.

Suppose if one of the interactions of individual A results in a trajectory where another interaction could occur with a target individual to further his primary intent. The trajectory is therefore in the form of a location where the other individual could be intersected.

Therefore one of the location coordinates for any individual could be inferred through interactions.

38.4 The ideal case with zero timeline diversion

Suppose the intent of individual A for every interaction is the primary intent of the lifetime, then each interaction should result in the most effective trajectory to further his primary intent.

The trajectory is defined initially by the location reference which serves as the intersection point to the desired individual.

38.5 The average individual and his intersections

If an interaction is initiated with a primary intent then the effect the primary intent has on the trajectories of each individual in the interaction could be assumed to be random, however for each individual, this results in x trajectories depending on his perception.

Where each trajectory is a location reference to an individual

The perception of each individual is assumed to be random and is in a superposed state that results in the objective geometric movement of individuals.

38.6 Deducing the perception of the individual

If the exact movement of the individuals could be simulated using location-time data, then the nature of the individual's perception could be deduced or regressed with his interaction data (individuals he interacts with, duration of interactions,etc)

38.7 The timeline map for individual A

Individual A at each interaction with N random individuals, has a possibility of (x * N) trajectories possible from any current moment in time.

Suppose if x trajectories are presented at the end of each interaction, then individual A will choose the trajectory that his attention is naturally drawn to.

Suppose the intent of any interaction could be interpreted in either a moral or an immoral way then the perception of the individual holds the definition of morality and immorality.

The attention of individual A is drawn to the primary intent of the individual's life and therefore serves as a GPS for his life path.

38.8 Illustration

The trajectory of the individual on Earth Territory is as follows :

When Individual A has an interaction with the following individuals/groups,

Interaction with family :

Interaction with father :

Interaction with mother :

Interaction with friend Q :

...

With each interaction, locations are inferred

Locations serve as an interaction initiation with specific individuals

....

The cycle repeats till it ends